

Understand your data:

observational selection effect





Funded by the European Union

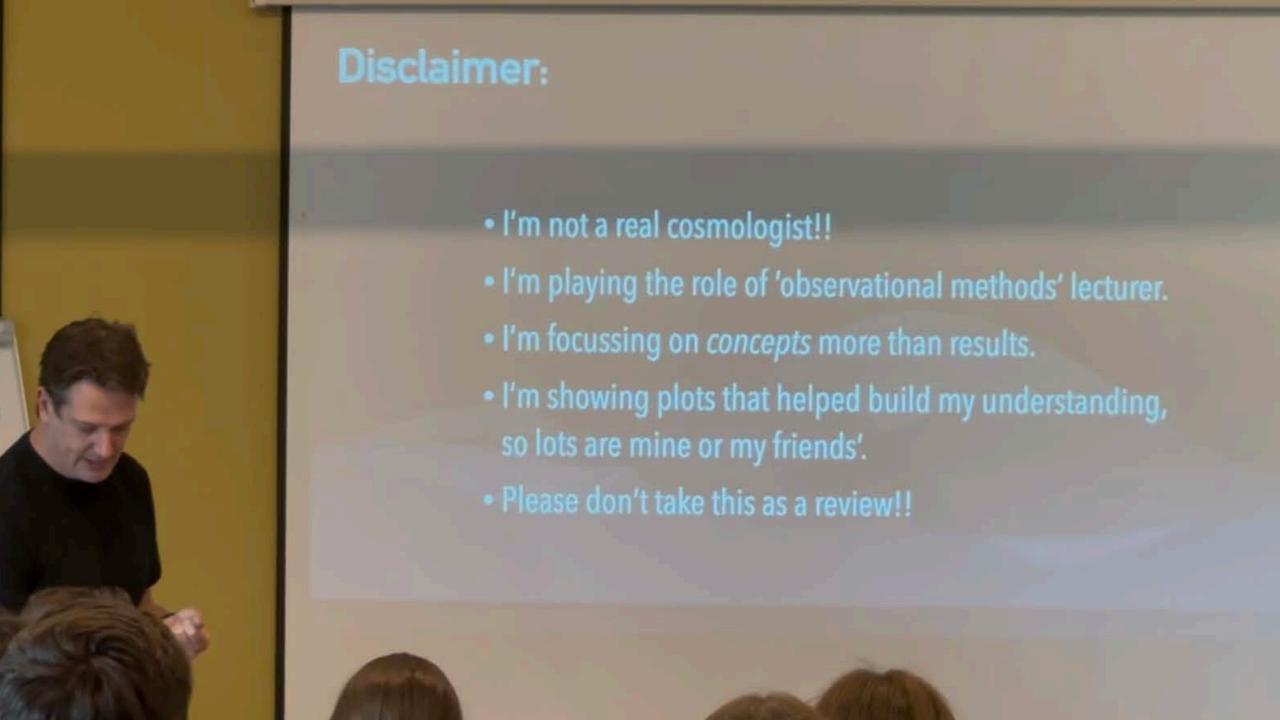


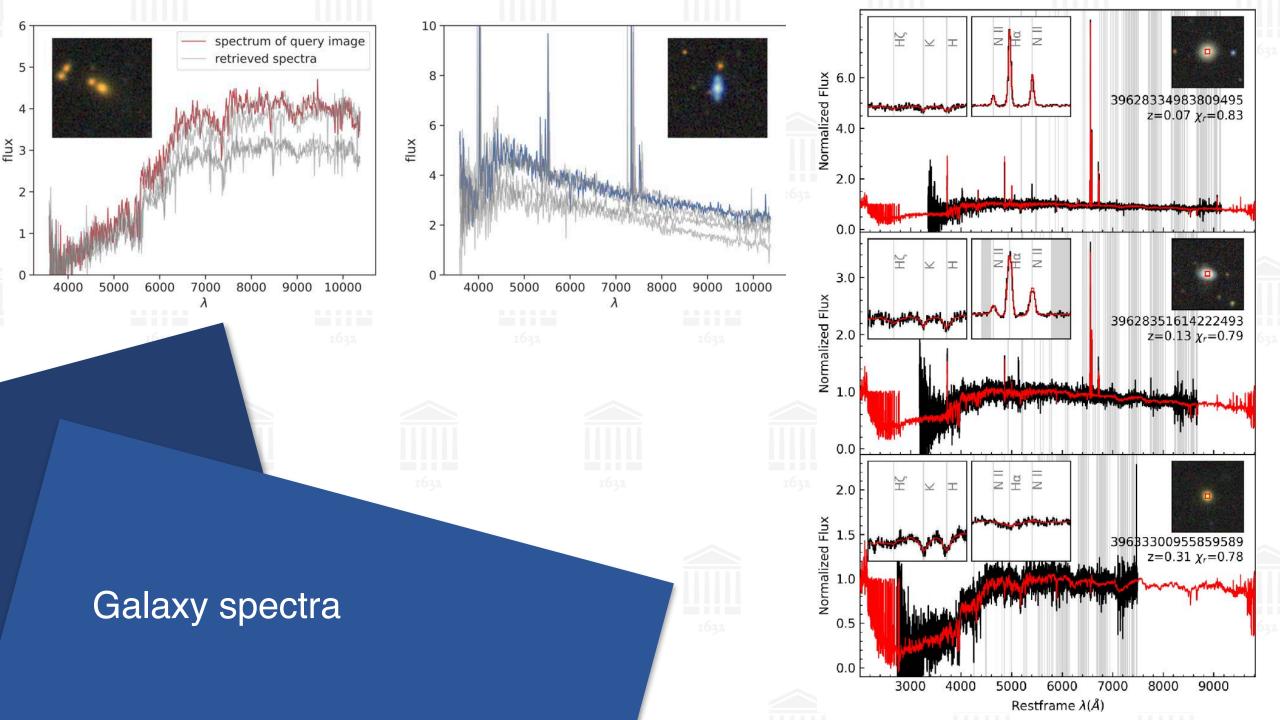
Observed Cosmic Web (Tempel lectures)

- Cosmic Web as revealed in observations
- Galaxy redshift surveys biased overview
- 4MOST WAVES and 4HS surveys mapping the Universe
- Preparind a redshift survey 4MOST example

- Understand your data: observational selection effects
- Galaxy Groups in redshift surveys
- Filaments in the Cosmic Web
- Selected science topics in Tartu Observatory

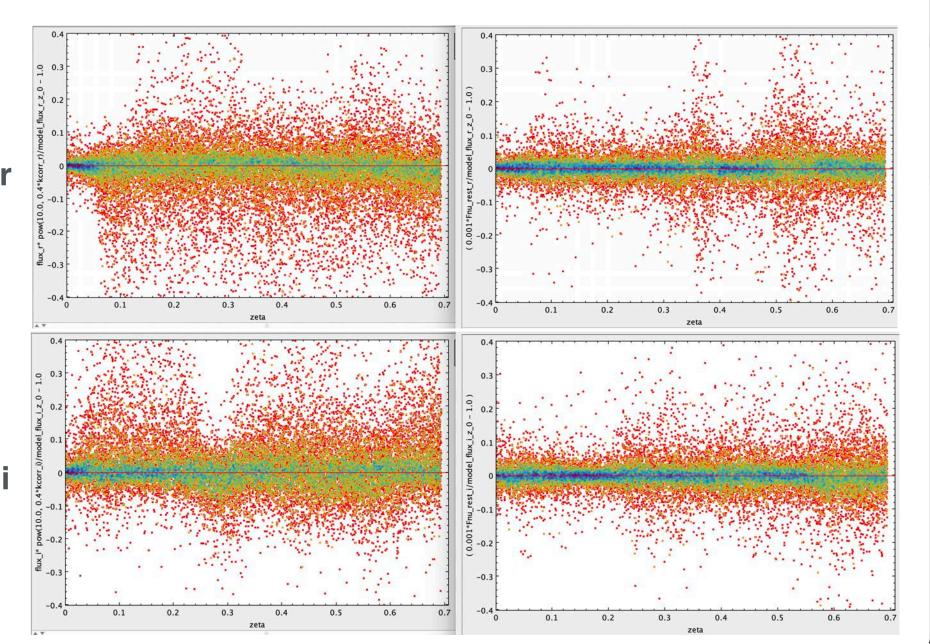


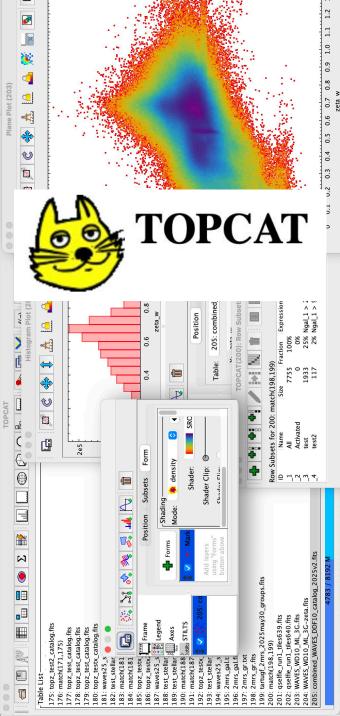


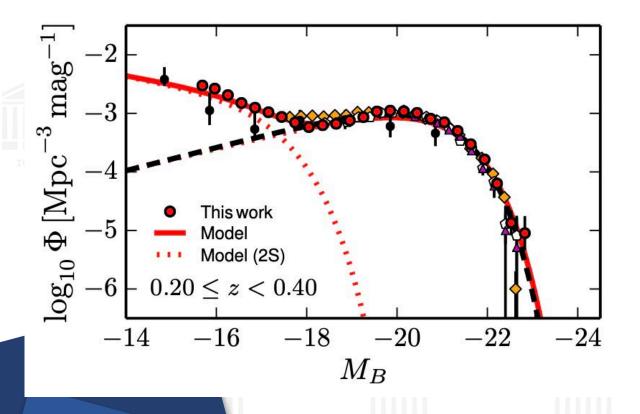


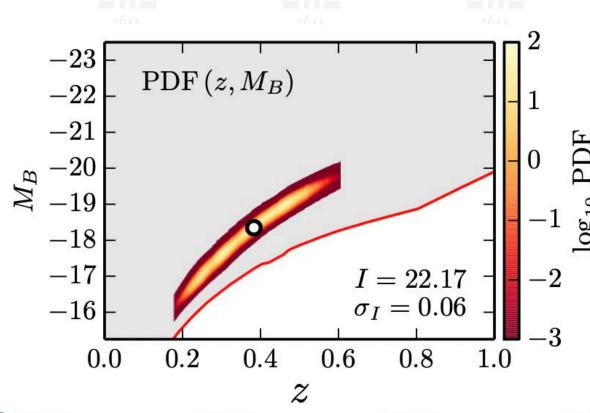
Blanton et al.

TOPz k-corrections









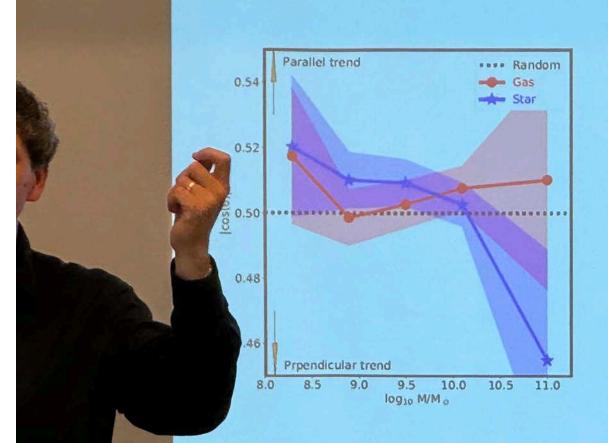
Redshift uncertainty

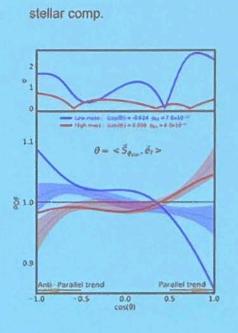
No one trusts simulations, except the person who made them!

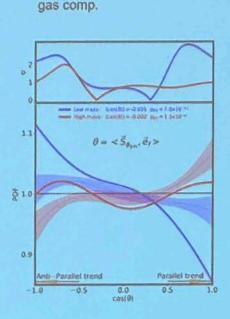
Everyone trusts observations, except the person who collected the data!



Spinning Filaments – Spinning Gals: parallel vs. anti-parallel ?







Wang et al. 2025

Sample MaNGA galaxies (IFU)

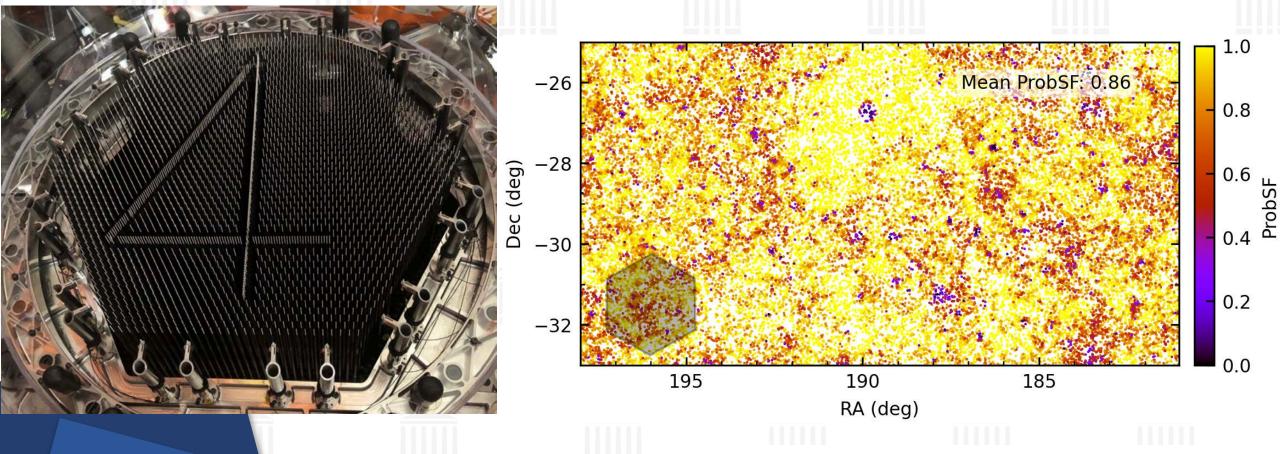






Spectroscopic redshift vs probability z_photo< 0.2 Masking stars, ghosts, artefacts z = 0.20.8 0.6 Star-galaxy separation 0.2 Galaxy 0.0 0.2 0.8 In(1+z_spec) Photo-z preselection **TOPz** 0.4 \$TOP2 08:46:00.0 08:45:00.0 08:44:00.0 08:43:00.0 Right Ascension / H:M:S UMAP 1 0.2 0.4

4MOST WAVES survey - target catalogue preparation



Fixed fibre pattern

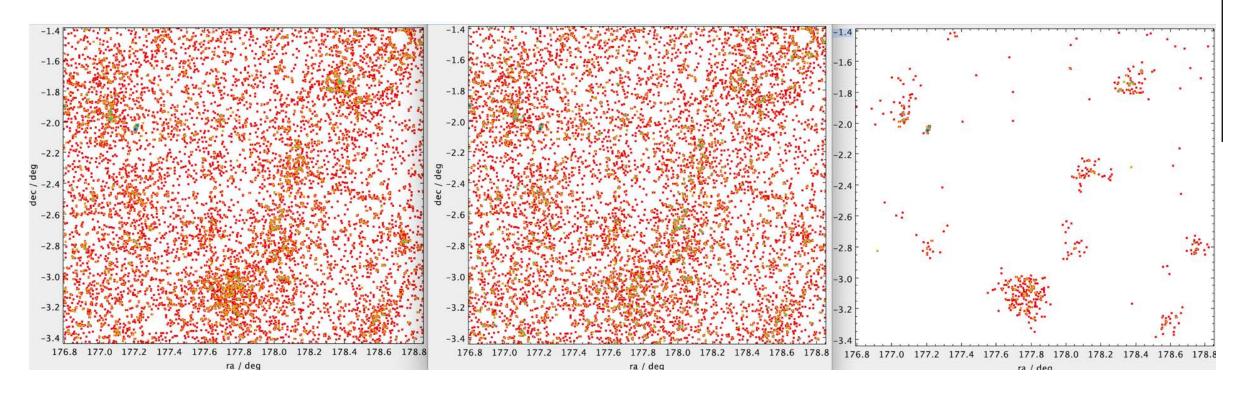
Limited patrol area for each fibre

Efficiency vs completeness

- all fibres are used
- not all targets are observed
- all targets are observed
- many fibres are empty

Incompleteness in High-Density Areas

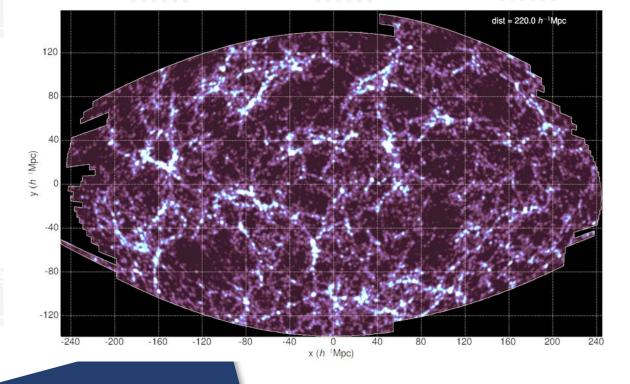
4MOST selection function



Original catalogue

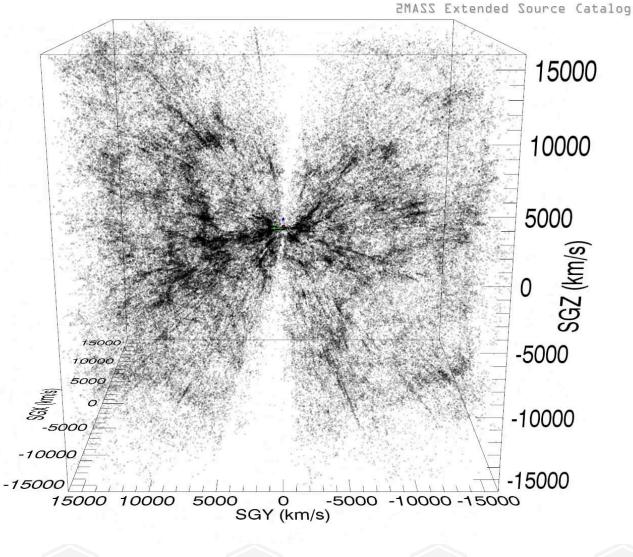
Observed galaxies

Unobserved galaxies



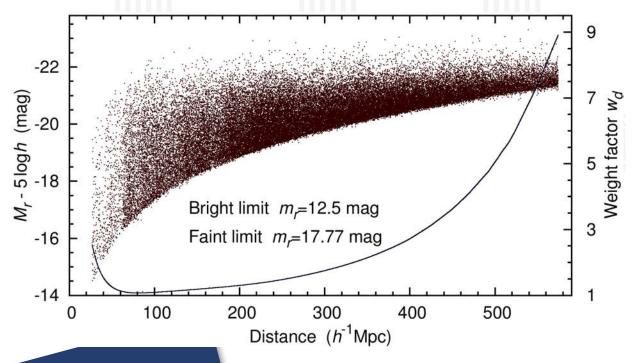
Fingers of god effect

Tully & Fisher (1978), IAU Symposium 79, Large Scale Structures in the Universe, Tallinn, 1977



Credit: Tully et al. 2014

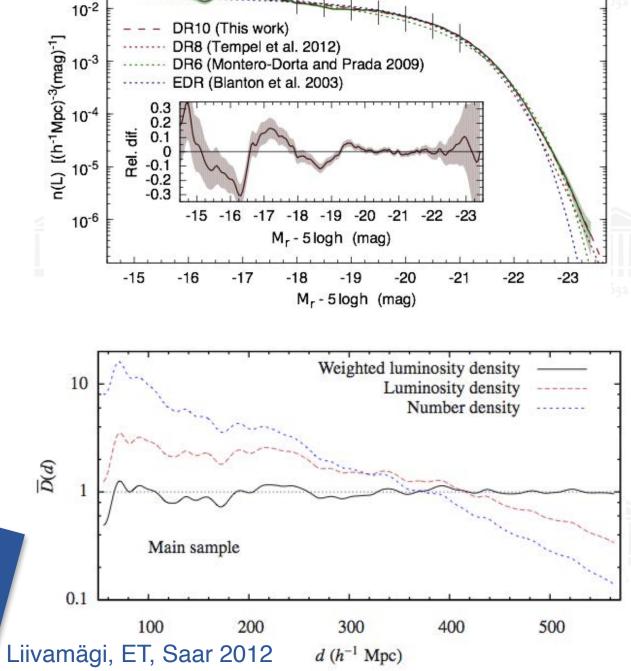




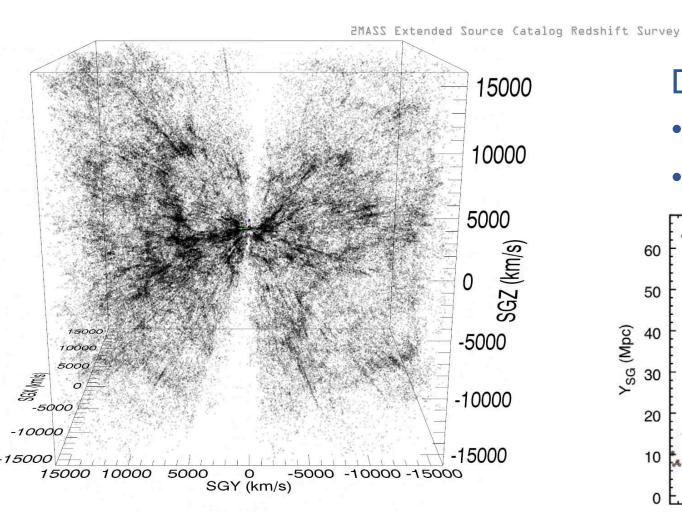


Flux-limited survey effect

Fainter galaxies are missing



Observations: selection effects



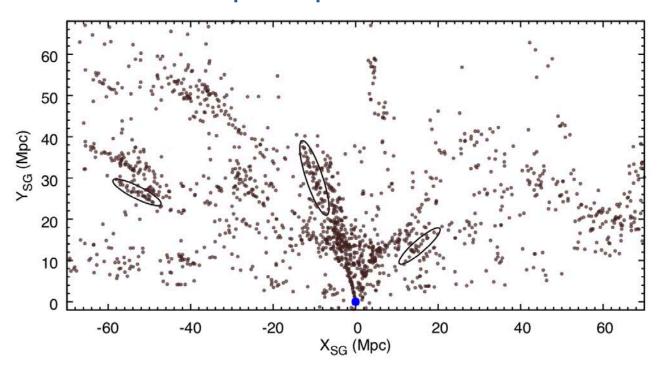
Courtesy: Tully et al. 2014

Fingers-of-god effect:

Tully & Fisher (1978), IAU Symposium 79, Large Scale Structures in the Universe, Tallinn, 1977

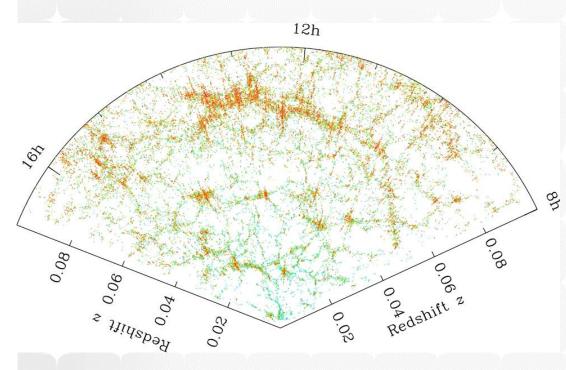
Detecting galaxy groups and clusters:

- Friends of friends
- Marked point processes



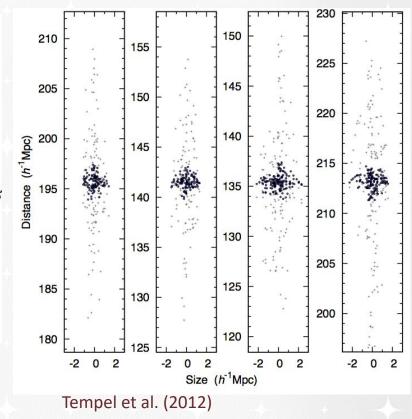
Tempel et al. (2012, 2014, 2017, 2018) 119

Observations: selection effects



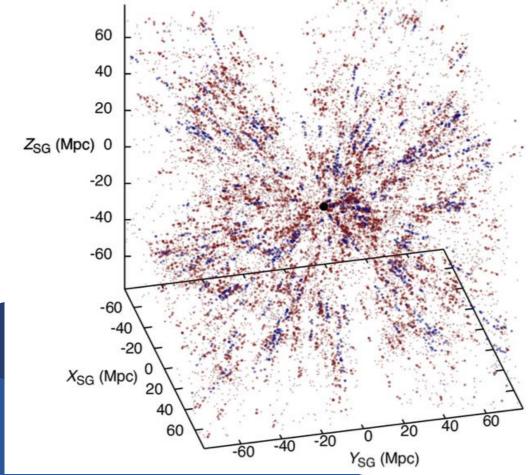
Finger-of-god effect:

Tully & Fisher (1978), IAU Symposium 79, Large Scale Structures in the Universe, Tallinn, September 12-16, 1977



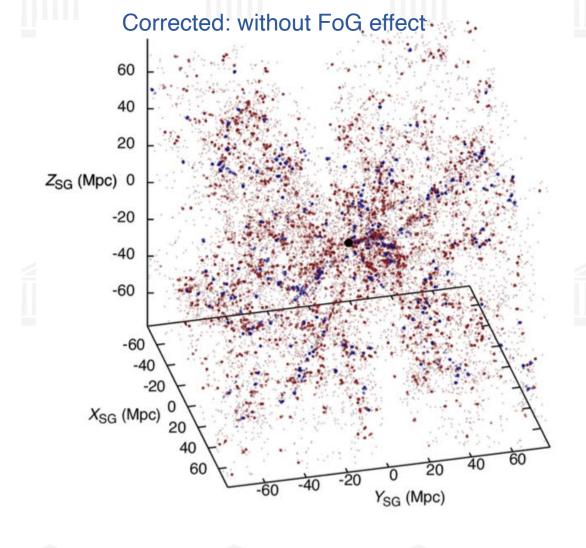
Using friends-of-friends galaxy groups, we suppress the finger-of-god distortions.

Observed: with FoG effect



Fingers of god effect

Using galaxy groups to spherise groups



Detecting groups in redshift surveys: ET et al. 2012, 2014, 2016, 2017, 2018



Luminosity function of galaxies

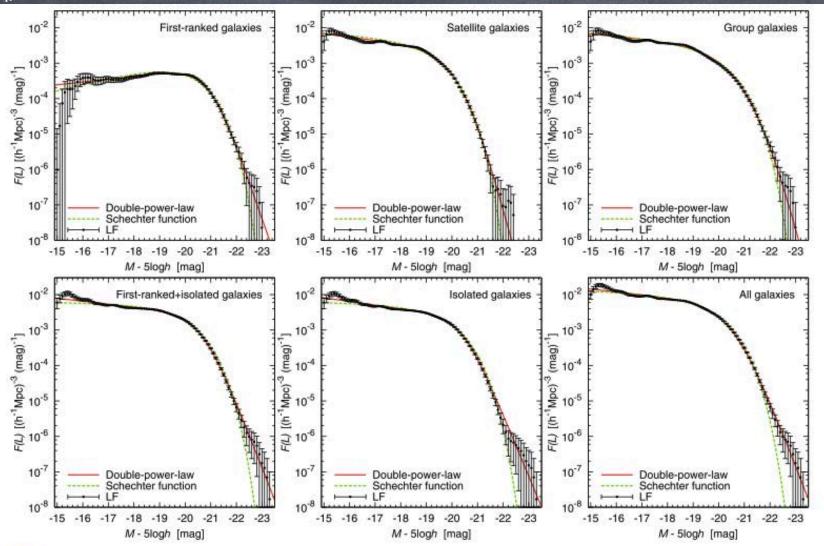


Fig. 13. Differential LFs for various galaxy populations: first-ranked, satellite, first-ranked+satellite (group), first-ranked+isolated, isolated and all galaxies. The points are LFs, using 2dF galaxy catalogue. Error-bars are Poisson $1-\sigma$ errors. The red solid line is the double-power law and the green dashed line is the Schechter function.

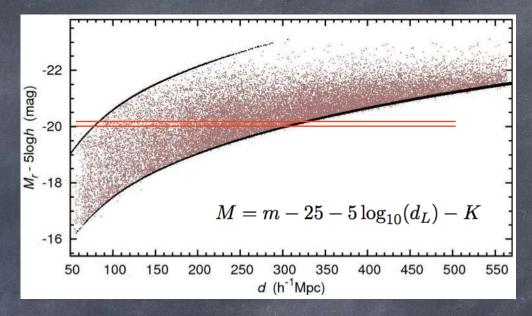


Luminosity function - new method

Standard 1/V_{max} method:

$$n(L)\mathrm{d}L = \sum_i rac{\mathbf{I}_{(L,L+\mathrm{d}L)}(L_i)}{V_{\mathrm{max}}(L_i)}$$

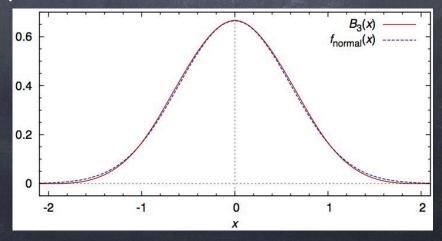
(binned density histogram)



Sum of kernels centered at the data points:

$$n(L) = \sum_{i} \frac{1}{V_{\max}(L_i)} \frac{1}{a_i} K\left(\frac{L - L_i}{a_i}\right)$$

(adaptive kernel estimation)

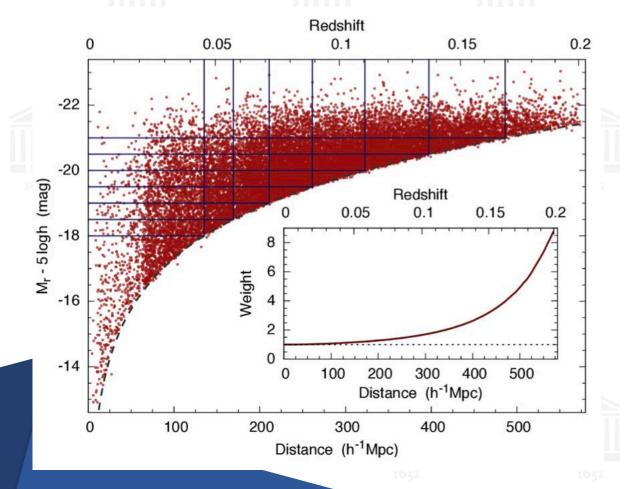


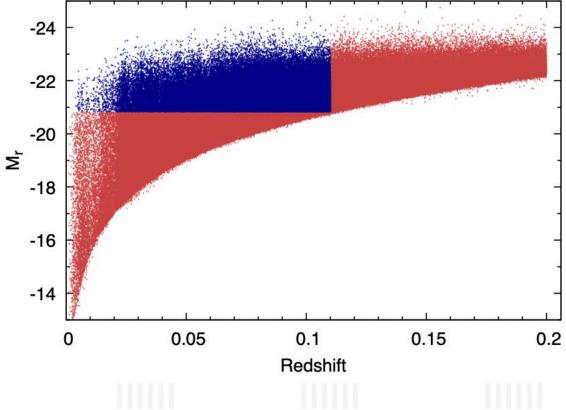
Error bars: smoothed bootstrap

Luminosity function of galaxies

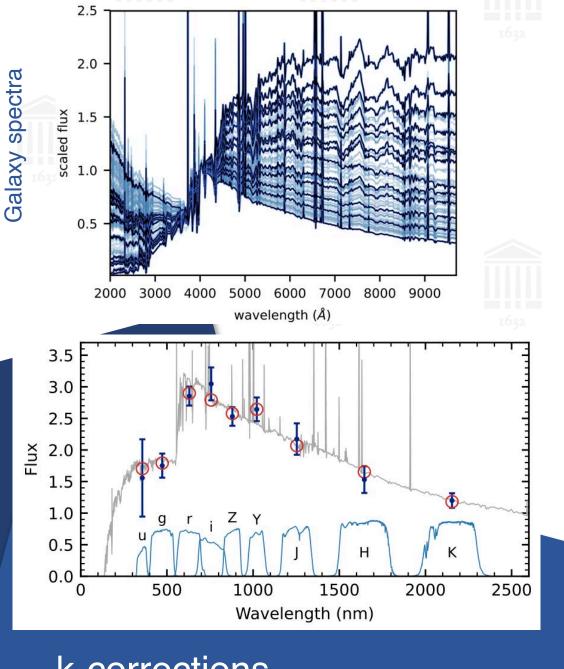
- flux-limited survey
- k-corrections absolute luminosity
- galaxy dependent limiting distances
- dust effects on luminosity
- inclination angle effects
- surface brightness limitations
- incompleteness in redshift surveys
- redshift to distance conversion (pec vel)





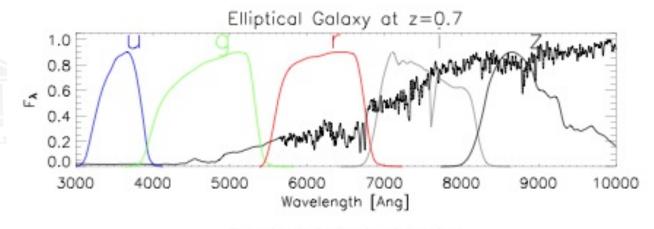


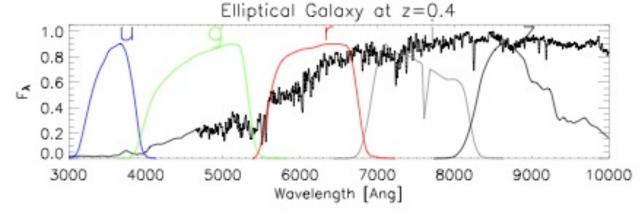
$$M_{\lambda} = m_{\lambda} - 25 - 5 \log_{10}(d_L) - K,$$

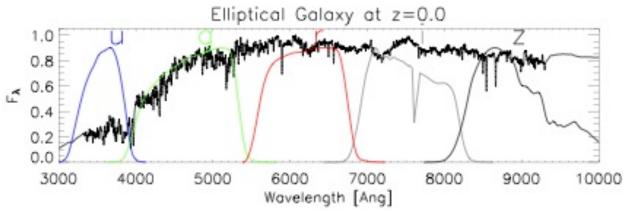


k-corrections

Same galaxy at different redshifts









Galaxy modeling

- Simple bulge+disc model...
- ... add dust disc to improve inclination angle estimation
- ... use dust disc to estimate the sign of inclination

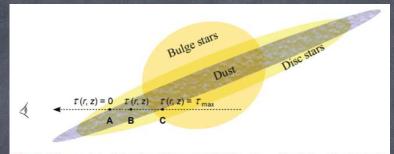
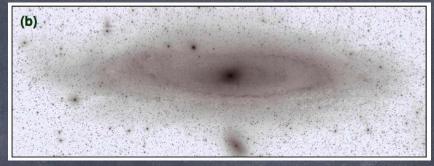
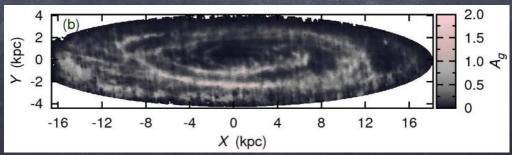


Fig. 1. Geometry of the dust disc model. The line-of-sight optical depth for three positions A–C is indicated. The figure is illustrative only.





Tempel, Tamm, Tenjes (2010)
Tempel, Tuvikene, Tamm, Tenjes (2011)
Tamm, Tempel, Tenjes, Tihhonova, Tuvikene (2012)

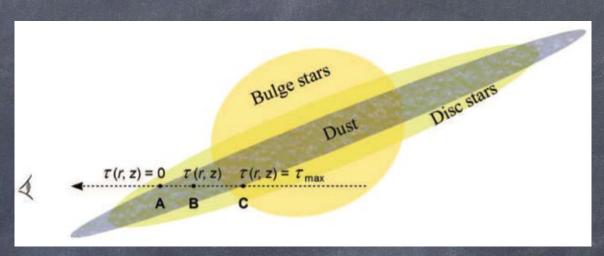


Dust extinction in spiral galaxies

Model for dust attenuation calculation in galaxies

Attenuation depends on:

galaxy viewing angle, galaxy stellar structure, dust disc geometry and dust properties.



$$l(a) = l(0) \exp \left[-\left(rac{a}{ka_0}
ight)^{1/N}
ight]$$

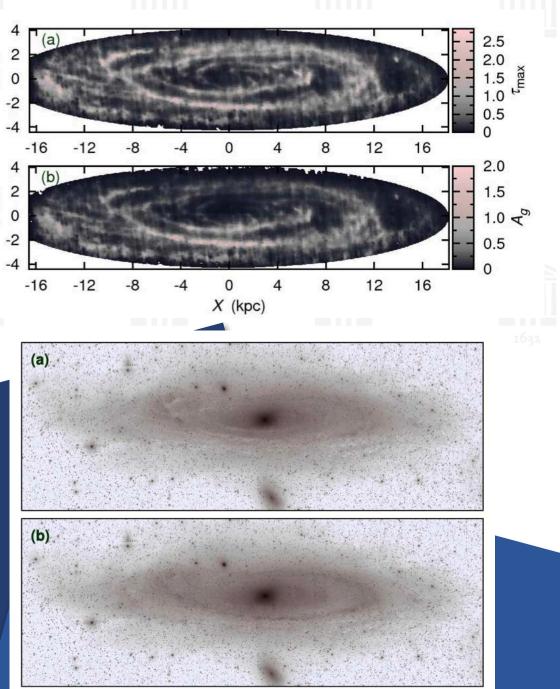
$$L(X,Y) = \int\limits_X^\infty rac{\sum\limits_{j=1}^2 \left[l(r,z_j)\,\mathrm{e}^{- au(r,z_j)}
ight]}{\sin i\,\sqrt{r^2-X^2}} r\,\mathrm{d}r,$$

$$z_{1,2}=rac{Y}{\sin i}\pmrac{\sqrt{r^2-X^2}}{ an i},$$

$$l(a) = l(0) \exp\left[-\left(rac{a}{ka_0}
ight)^{1/N}
ight] \ T(r,z) = au_{ ext{max}}(X,Y) rac{\int\limits_{ ext{A}}^{ ext{B}} n_{ ext{dust}}(s) \, \mathrm{d}s}{\int\limits_{ ext{A}}^{ ext{D}} n_{ ext{dust}}(s) \, \mathrm{d}s} \ T(r,z) = au_{ ext{max}}(X,Y) rac{\int\limits_{ ext{A}}^{ ext{B}} n_{ ext{dust}}(s) \, \mathrm{d}s}{\int\limits_{ ext{A}}^{ ext{D}} n_{ ext{dust}}(s) \, \mathrm{d}s} \ n_{ ext{dust}}(r,z) = f_{ ext{dust}}(r) \cdot n(a) \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle \lambda \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle A(\lambda) \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle A(\lambda) \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle A(\lambda) \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle A(\lambda) \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle A(\lambda) \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle A(\lambda) \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) rac{\lambda^{eta}B(\lambda)}{\langle A(\lambda) \rangle \langle B(\lambda) \rangle} \ T_{ ext{max},f}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) = c_{f,\lambda'}F_{\lambda'}(X,Y) = c_{f,\lambda',T'}F_{\lambda'}(X,Y) = c_{f,\lambda',T$$

$$n_{ ext{dust}}(r,z) = f_{ ext{dust}}(r) \cdot n(a)$$

$$\tau_{\max,f}(X,Y) = c_{f,\lambda',T'} F_{\lambda'}(X,Y) \frac{\lambda^{\beta} B(\lambda',T')}{(\lambda')^{\beta} B(\lambda,T(X,Y))}$$



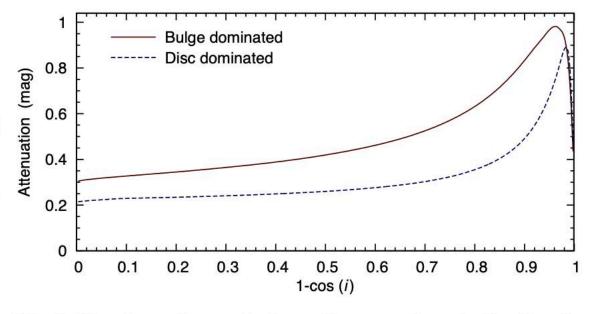


Fig.9. The dependence of attenuation on galaxy inclination for disc-dominated and bulge-dominated spiral galaxies.

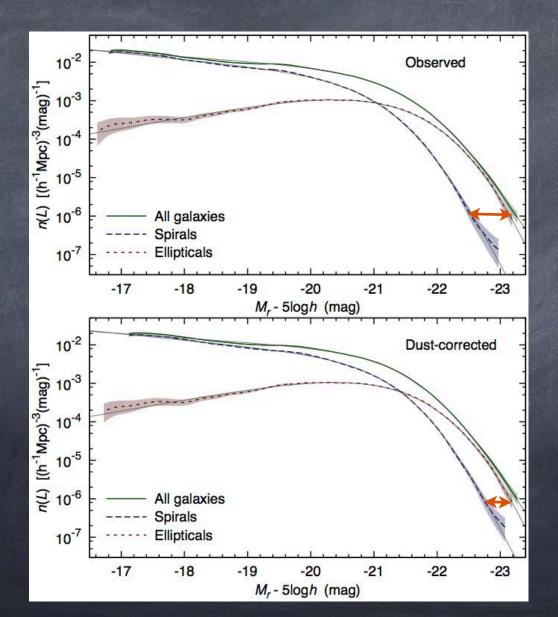
Is 3D modelling necessary?

$$\cos^2(i) = \frac{(a/b)^2 - q^2}{1 - q^2}$$

a/b - visible axial ratio q - disc flatness (0.1)



Dust extinction: luminosity function



Redshift-space distortion (RSD)

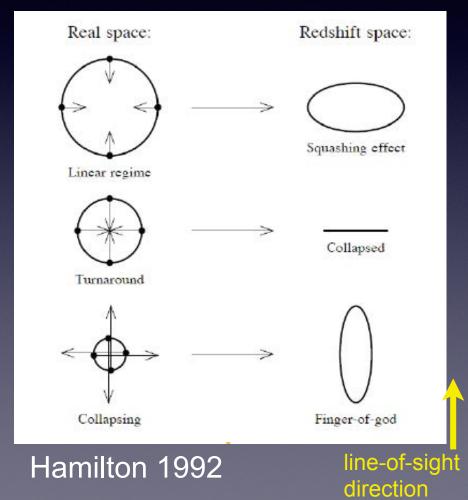
Peculiar motion of galaxies distort the observed (redshift-space) galaxy distribution

Linear regime

Coherent bulk motion squashes the galaxy distribution along the LOS direction
"Kaiser effect"

Nonlinear regime

Random motion of galaxies elongate the galaxy distribution along the LOS direction "Fingers-of-God effect"



Test of Gravity

Redshift-space galaxy power spectra in linear regime

$$P_{\rm g}(k,\mu) = (b + f)^2 P_{\rm m}(k)$$
 (Kaiser1987)

b: linear galaxy bias $\mu = k_{\parallel}/k$

f: growth rate

Growth rate is a key probe to test gravity

$$f \equiv \frac{d \ln D}{d \ln a} \simeq \Omega_m(z)^{\gamma}$$

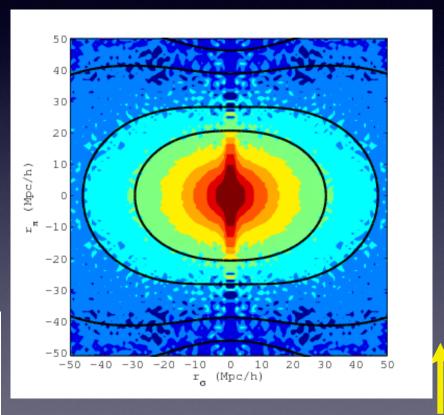
(Peebles 1976, Lahav et al. 1991)

 $\gamma \simeq 0.55$ for ΛCDM

 $\gamma \simeq 0.68$ for flat DGP (e.g., Linder & Cahn 2007)

 $\gamma \simeq 0.43$ for f(R) (e.g., Hu & Sawicki 2007)

2-point correlation functions for BOSS CMASS samples $\xi(r_p, r_{\pi})$



Reid et al. 2012

line-of-sight direction

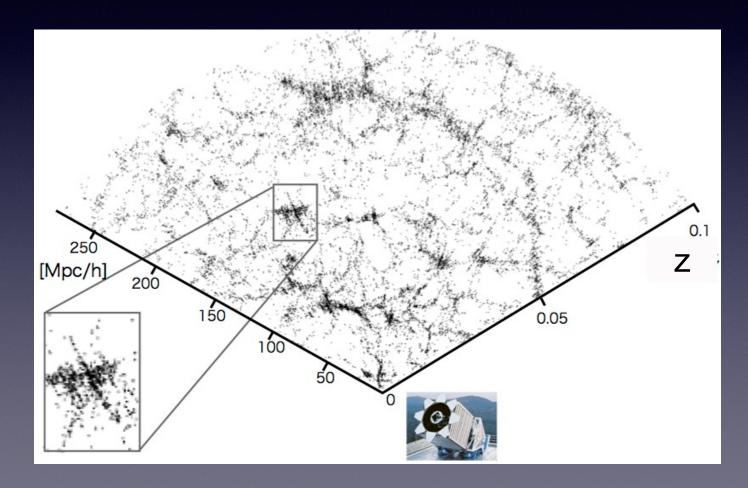
a=1/(1+z)

D(a) - linear growth factor



Mass

Nonlinear redshift-space distortion due to internal motion of galaxies in the host halos



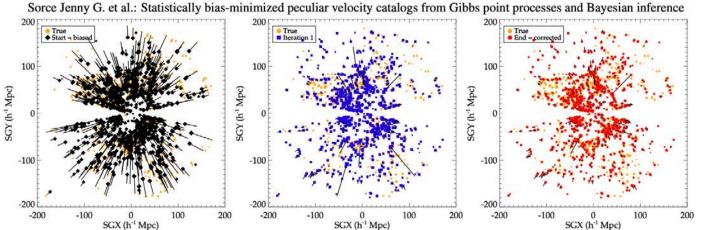
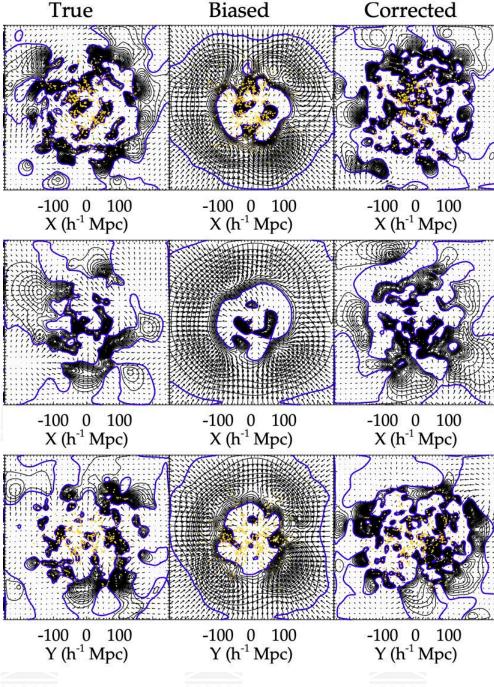


Fig. 4. Galaxies in 5 h^{-1} Mpc thick slices of the XY supergalactic plane. From left to right: Black lines show the projected distances between true (yellow filled circles) and biased (black filled diamonds), after n_{mh} Metropolis Hastings loops but no cooling for the n datapoints (in the text Iteration 1, blue filled square) and, at the end of all loops (red filled circles), datapoint positions. The filled symbol sizes are proportional to velocities on a logarithmic scale. Note that because errors are large in the left panel, yellow filled circles are harder to distinguish. The algorithm reduces on the average errors on datapoint positions thus on their peculiar velocities: on average shorter black lines and by extension better matching filled symbol sizes of different colors.

X (h-1 Mpc) -100 0 100 X (h⁻¹ Mpc) -100 0 100



Sorce et al.



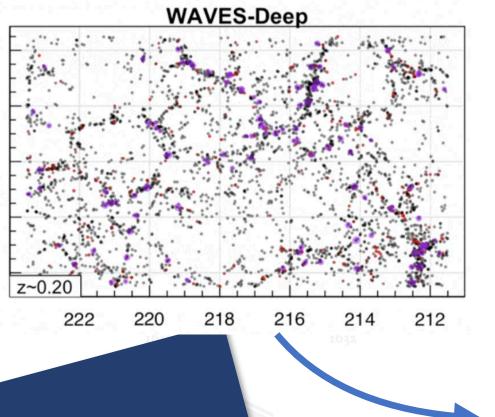


Galaxy Groups in redshift surveys

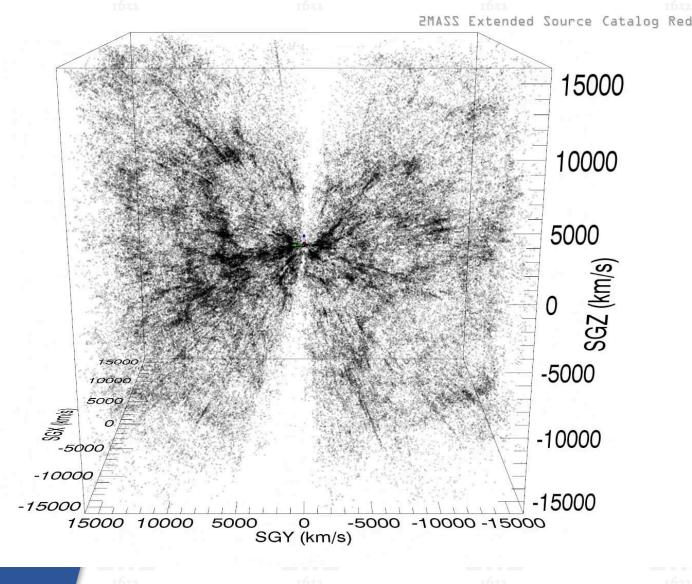




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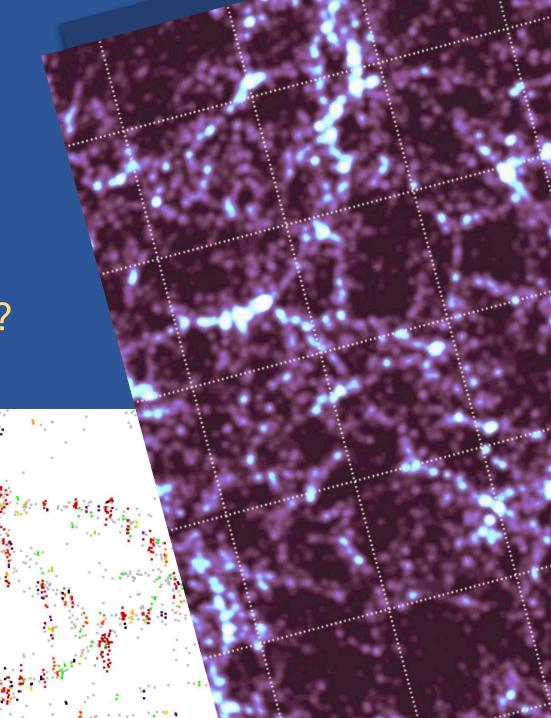
Cosmic web in the Local Universe

Group finding: three aspects

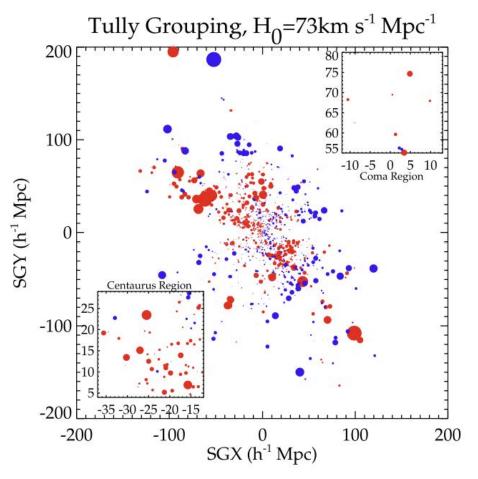
Where are the groups?
 Finding the group centres

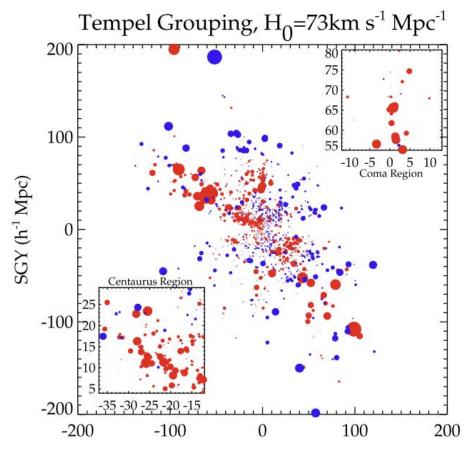
What galaxies belong to the groups?
 Group membership assignment

• Estimating group properties (i.e. group masses)



Impact of grouping

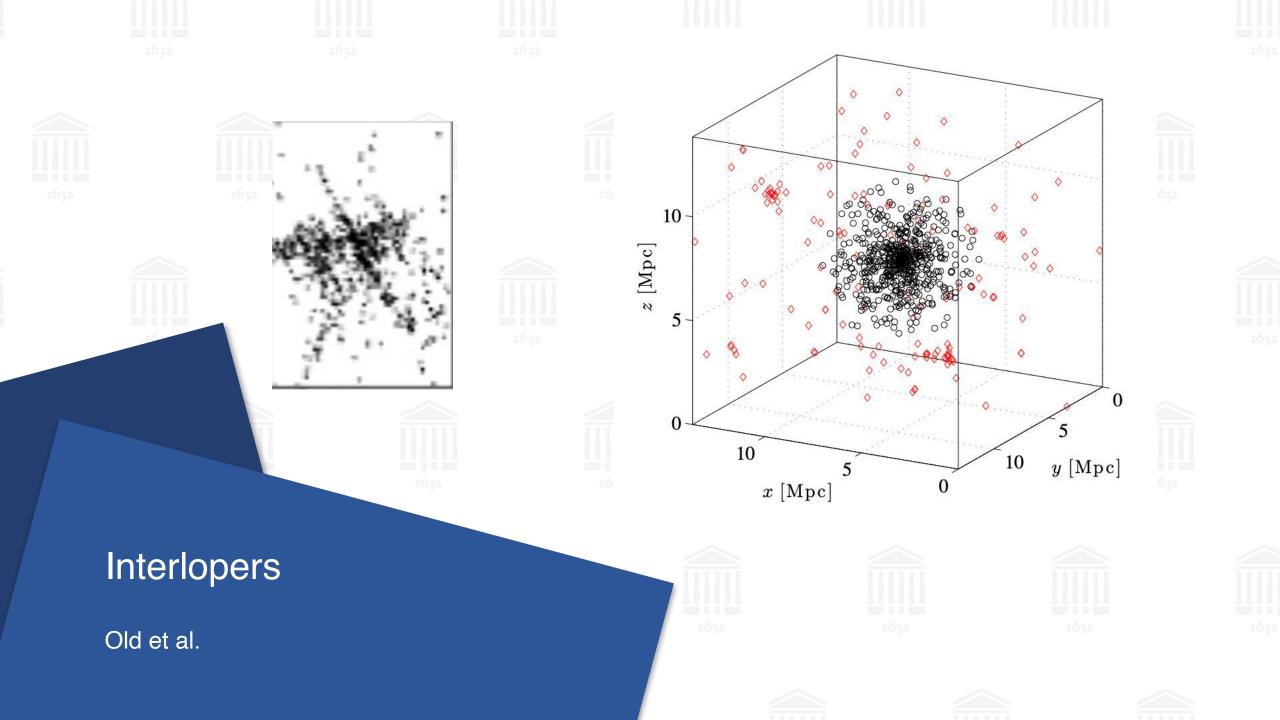


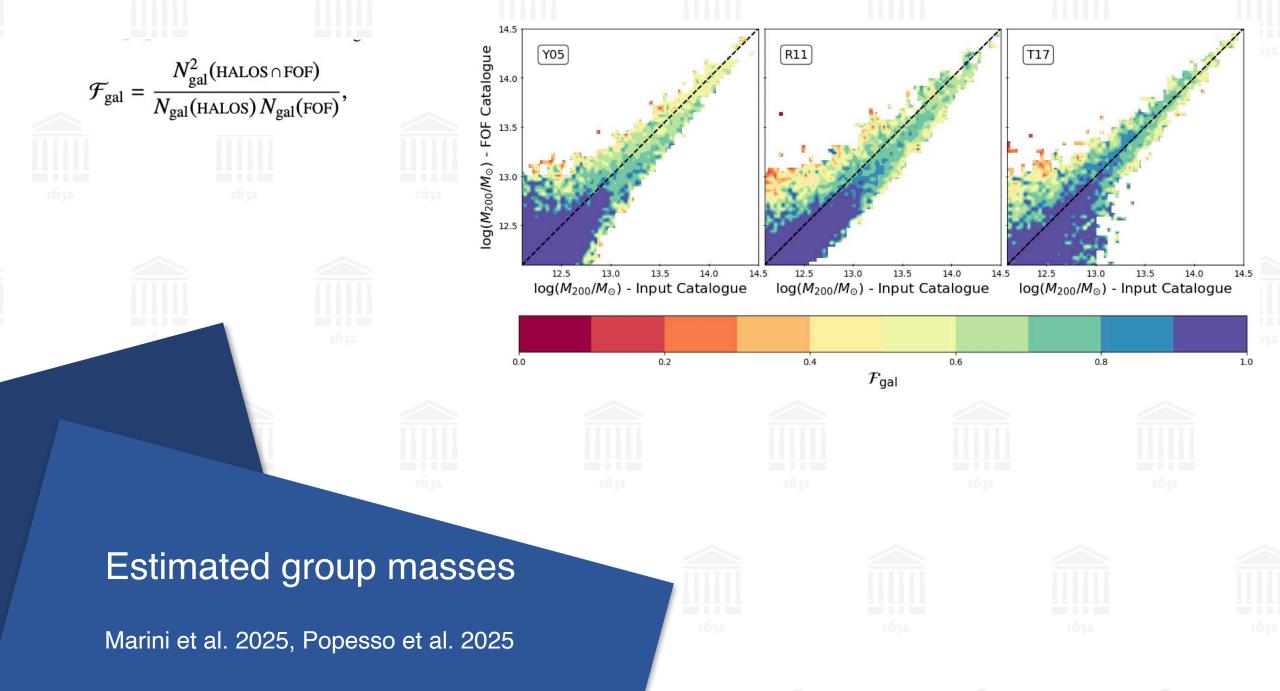


How does the grouping scheme affect the Wiener Filter reconstruction of the local Universe?

Jenny G. Sorce^{1,2★} and Elmo Tempel^{2,3}

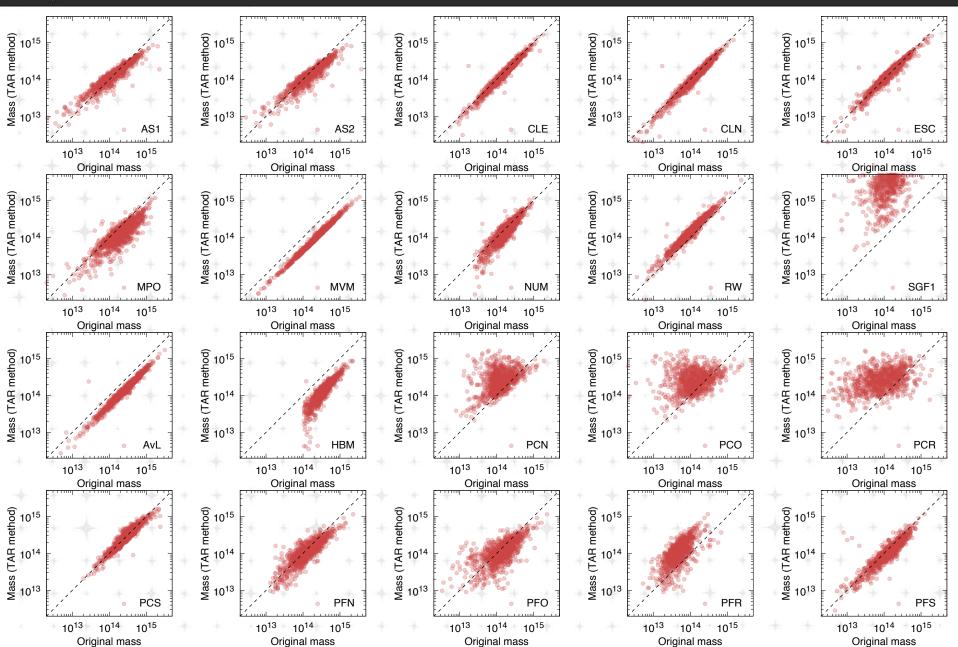
¹ CNRS, Observatoire astronomique de Strasbourg, UMR 7550, Université de Strasbourg, F-67000 Strasbourg, France ²Leibniz-Institut für Astrophysik, An der Sternwarte 16, D-14482 Potsdam, Germany



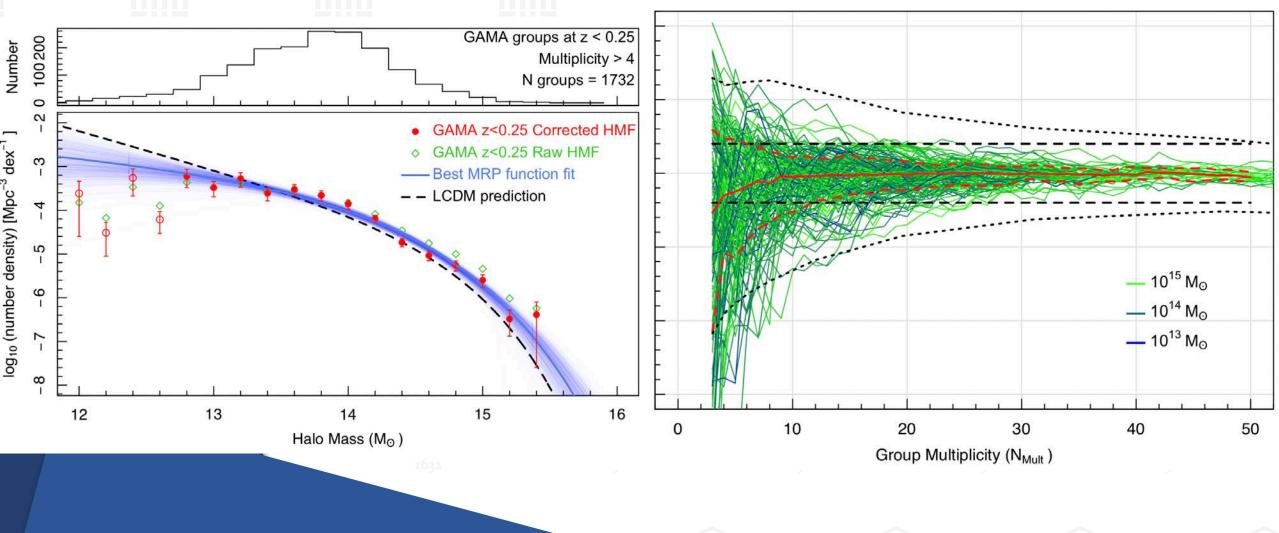




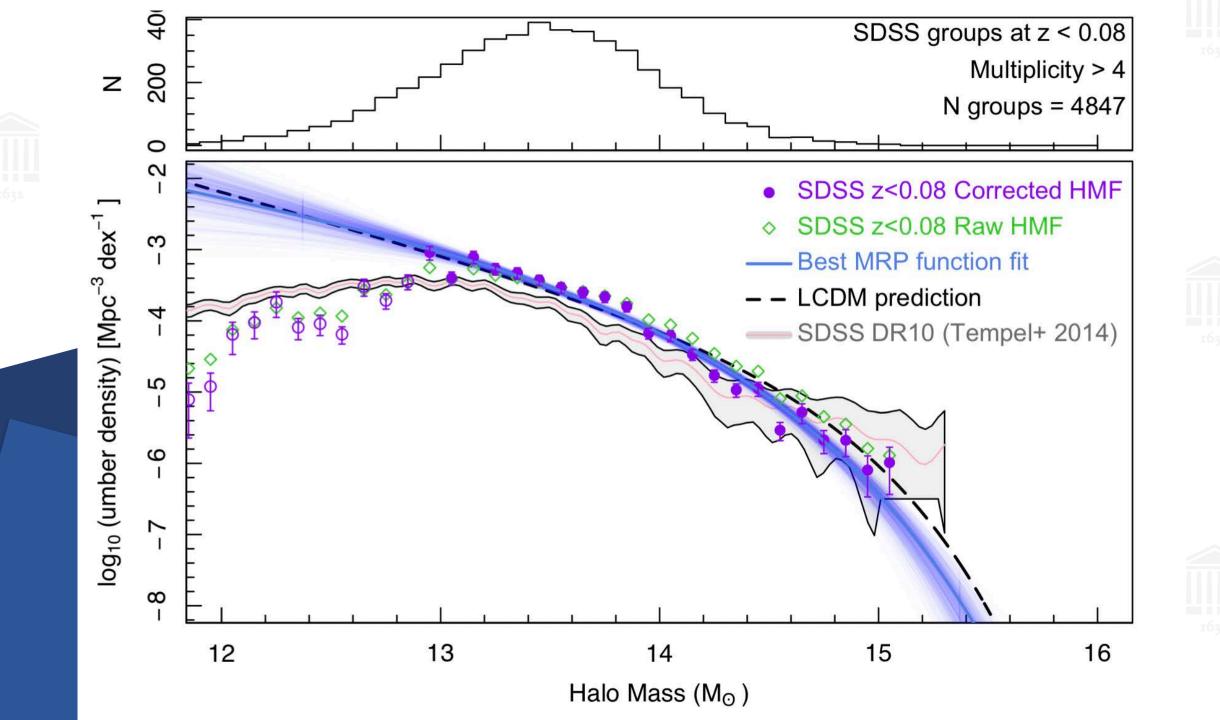
22 estimates of masses



Old et al.



Estimated group masses



Estimating group masses:

observed properties of groups

$$\sigma_v^2 = \frac{1}{(1+z_{\rm m})^2(n-1)} \sum_{i=1}^n (v_i - v_{\rm mean})^2$$

Radial velocity dispersion in

$$V = CZ$$

$$\sigma_r^2 = \frac{1}{2n(1+z_{\rm m})^2} \sum_{i=1}^n (r_i)^2$$

Group extent in the sky: $\frac{1}{2n(1+z_{\rm m})^2} \sum_{i=1}^{1} (r_i)^2$ r_i in co-moving coordinates, 1/2n since Rayleigh distribution

Dynamical mass estimate

From virial theorem (no free scaling parameters)

$$T = \frac{M_{\rm tot}\sigma_{\nu}^2}{2}, \qquad U = G\frac{M_{\rm tot}^2}{R_g}, \quad 2T = U \qquad \begin{array}{c} T & {
m kinetic \ energy} \\ P & {
m potential \ energy} \end{array}$$

$$M_{\rm vir} = 2.325 \frac{R_{\rm g}}{\rm Mpc} \left(\frac{\sigma_{\nu}}{100 \,{\rm km \, s^{-1}}} \right)^2 10^{12} M_{\odot}$$

- $R_{\rm g}$ Gravitational radius, which is directly linked (e.g. assuming NFW profile) to the group size in the sky plane
- σ_v Group velocity dispersion measured using galaxy redshifts

Estimating group masses:

virial theorem

$$M_{\rm tot} = 2.324 \cdot R_g \sigma_V^2$$

Mass in units of $10^{12}M_{sun}$ R_g in units of Mpc sigma_v in units of 100 km/s

$$\sigma_V = \sqrt{3}\sigma_{V1D}$$

Velocity dispersion.

Gravitational radius (R_g):

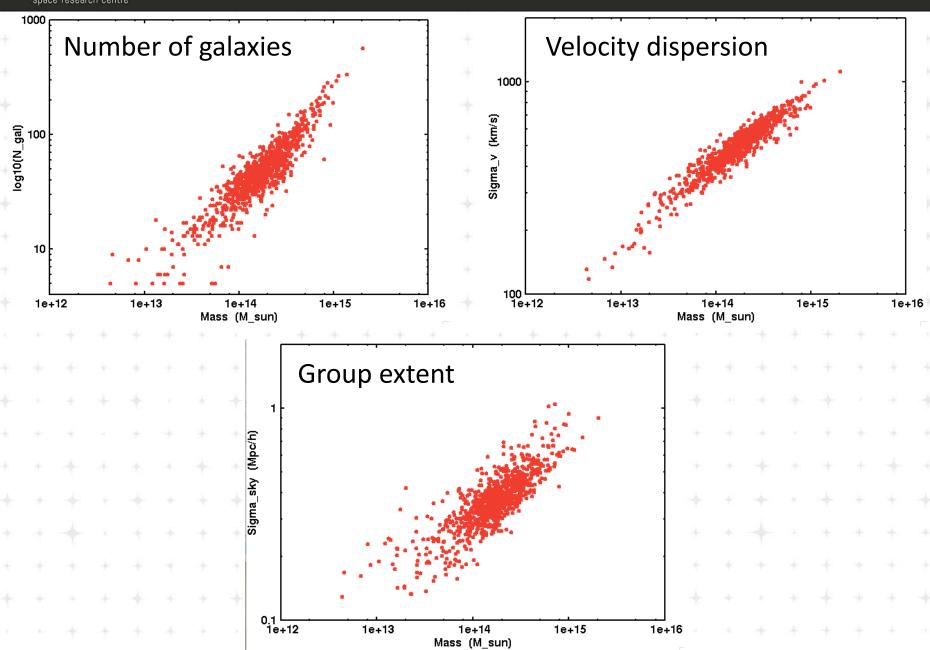
$$\frac{1}{R_g} = \frac{4\pi}{M^2} \int_{0}^{\infty} \frac{M(r)}{r} \rho(r) r^2 dr$$

Estimating group masses:

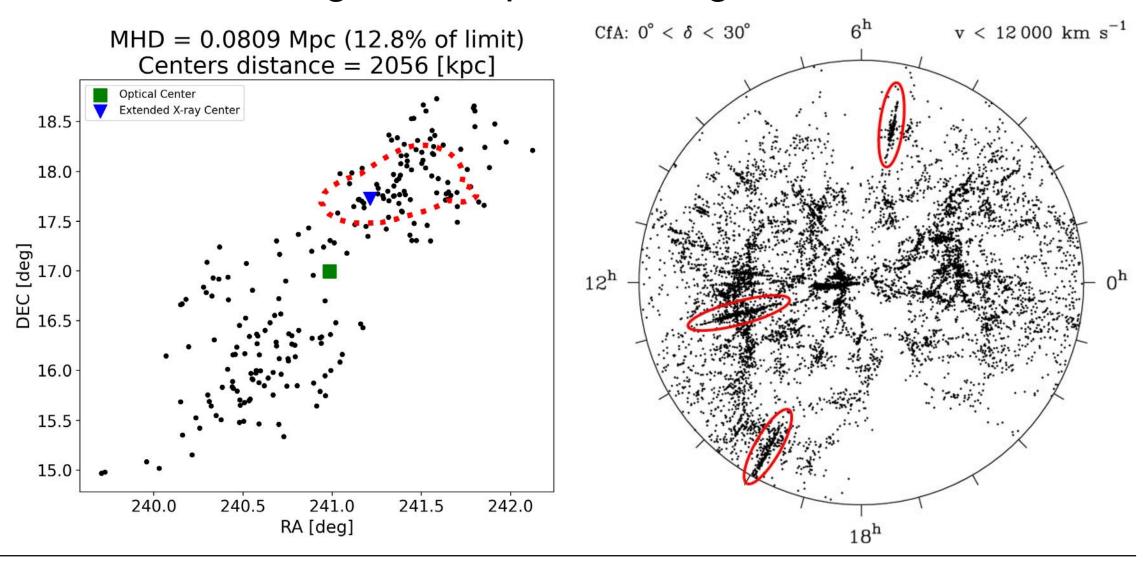
gravitational radius vs group extent in the sky

- ♦ We assume NFW profile.
- → Mass-concentration relation from Maccio et al. (2008).
- $Arr R_g = f(M_{200}).$
- \bullet For given mass M₂₀₀, we found R_g/sigma_R using NFW profile.
- ◆ Using this relation we transfer the observed group extent in the sky to gravitational radius R_g.
- ♦ We calculate the observed group mass using virial theorem.
- ◆ The final mass is found iteratively.

Groups in LC1



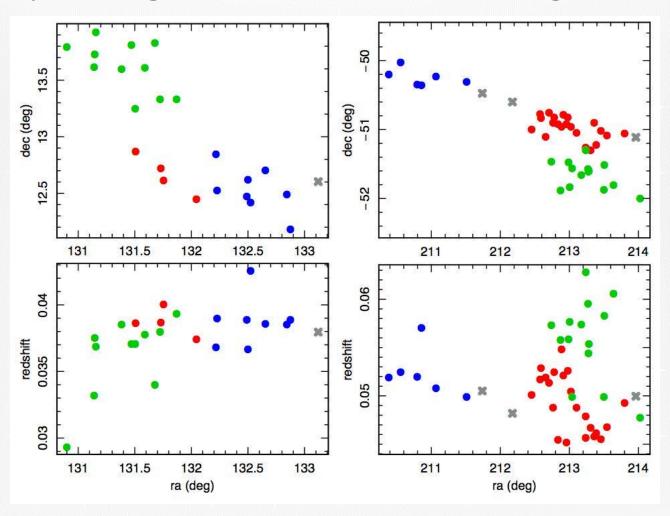
Merged Groups and Fingers-of-God



Credit: Jacob Kosowski

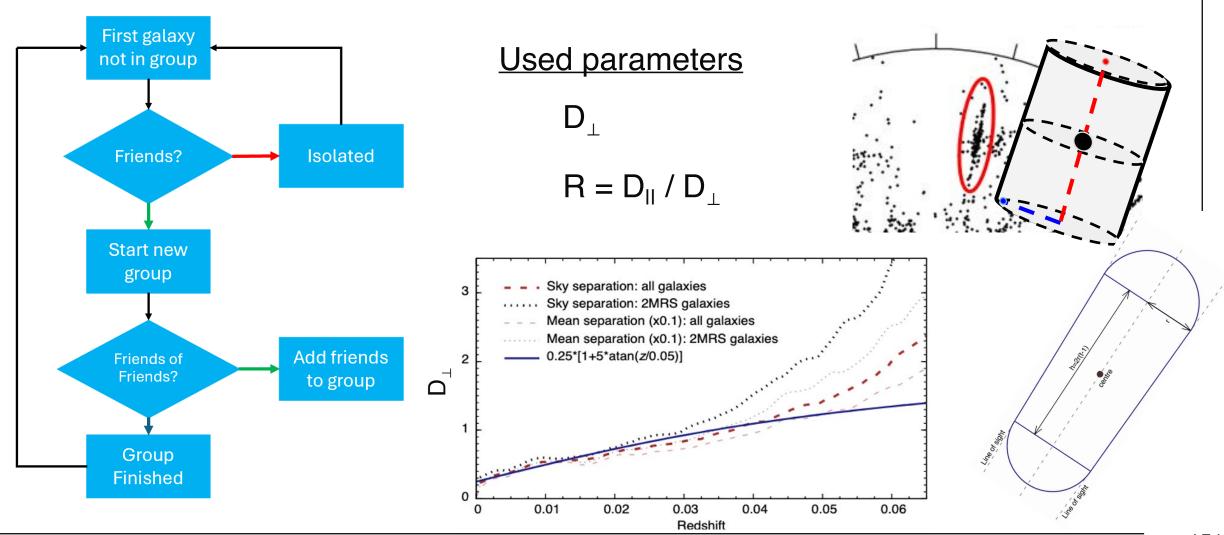


Improving Friends-of-Friends algorithm



Tempel et al. (2016)

Friends-of-Friends Parameters

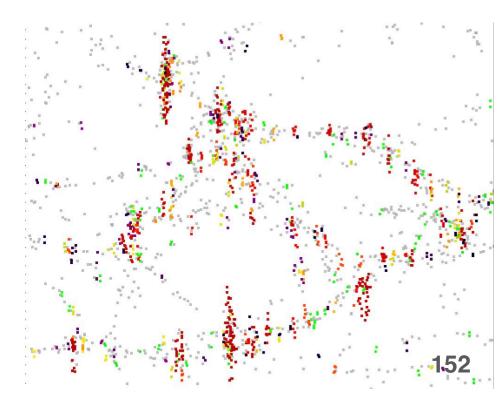


Credit: Trystan Lambert

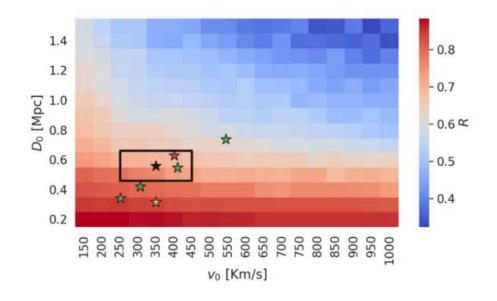
Friend-of-Friend group finder

- Linking length depends only on the mean number density of galaxies
- Different linking lengths in the sky plane and along the line of sight.
- 10x larger linking length along the line of sight

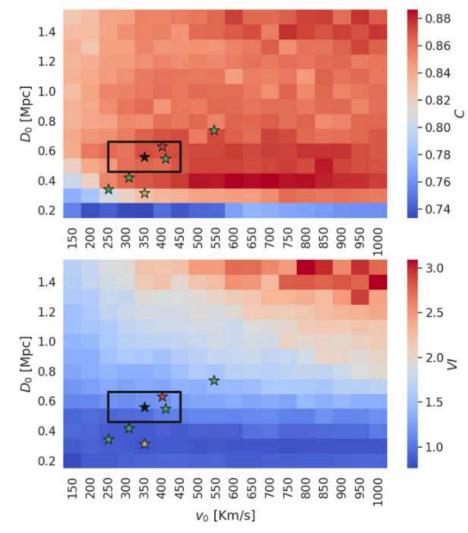
$$LL \approx 0.1 \cdot \left(\frac{Volume}{N_{gal}}\right)^{1/3}$$

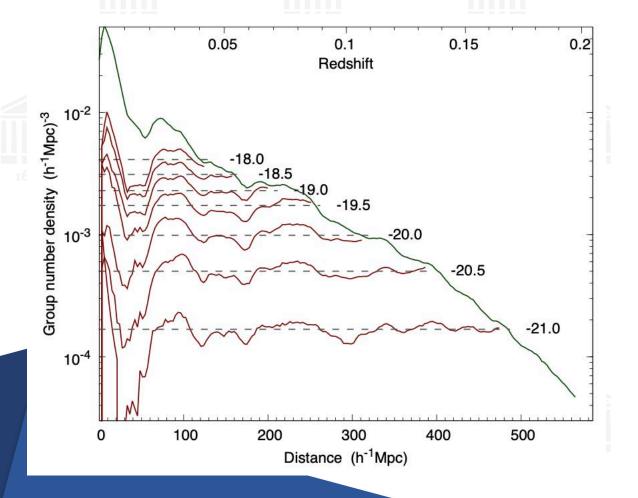


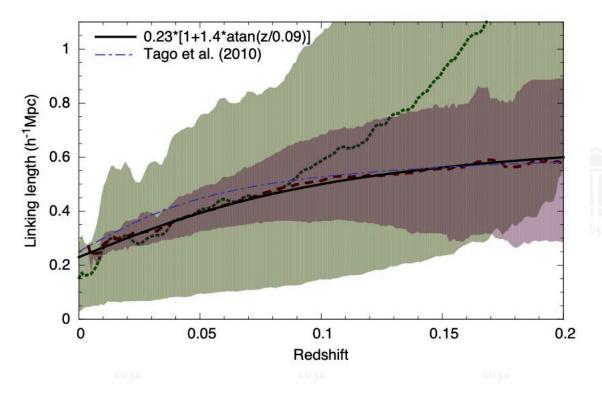
Lambert+2020 on the *not so* shallow 2MRS



- ★ Huchra & Geller, (1982)
- ★ Ramella et al., (1987) & Crook et al., (2007) HDC
- ★ Trasarti-Battistoni, (1998)
- ★ Crook et al., (2007) LDC
- ★ Tago et al., (2012) & Nurmi et al., (2013)
- This Work







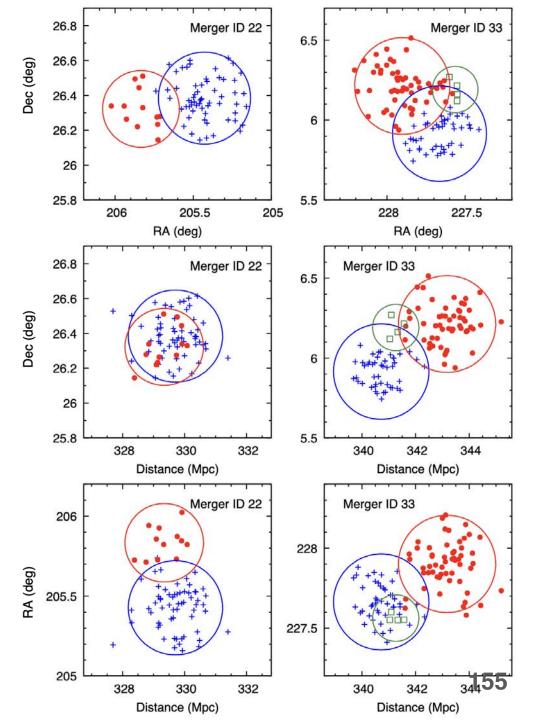
Linking length

Group refinement

- Often merging or closeby groups are taken as one group in FoF
- Multimodality analysis (mclust in R)
- Group membership refinement is based on estimates of the virial radius (in the sky plane) and escape velocity (along the line of sight) of the system.

$$\sigma_v^2 = \frac{1}{(1+z_{\rm m})^2(n-1)} \sum_{i=1}^n (v_i - v_{\rm mean})^2$$

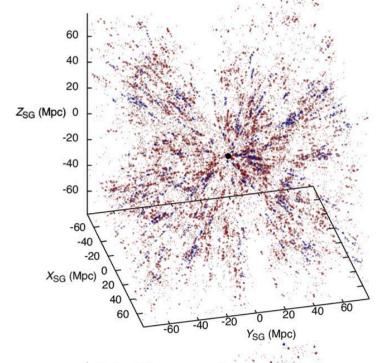
$$\sigma_{\text{sky}}^2 = \frac{1}{2n(1+z_{\text{m}})^2} \sum_{i=1}^{n} (r_i)^2$$

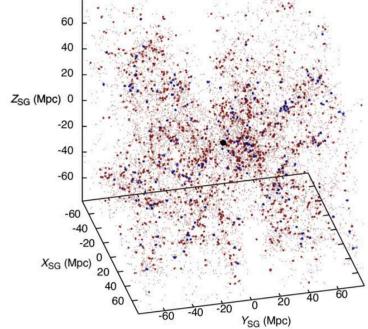


$$d_{\rm gal} = d_{\rm group} + \left(d_{\rm gal}^* - d_{\rm group}\right) \frac{\sigma_{\rm sky}}{\sigma_{\nu}/H_0},$$

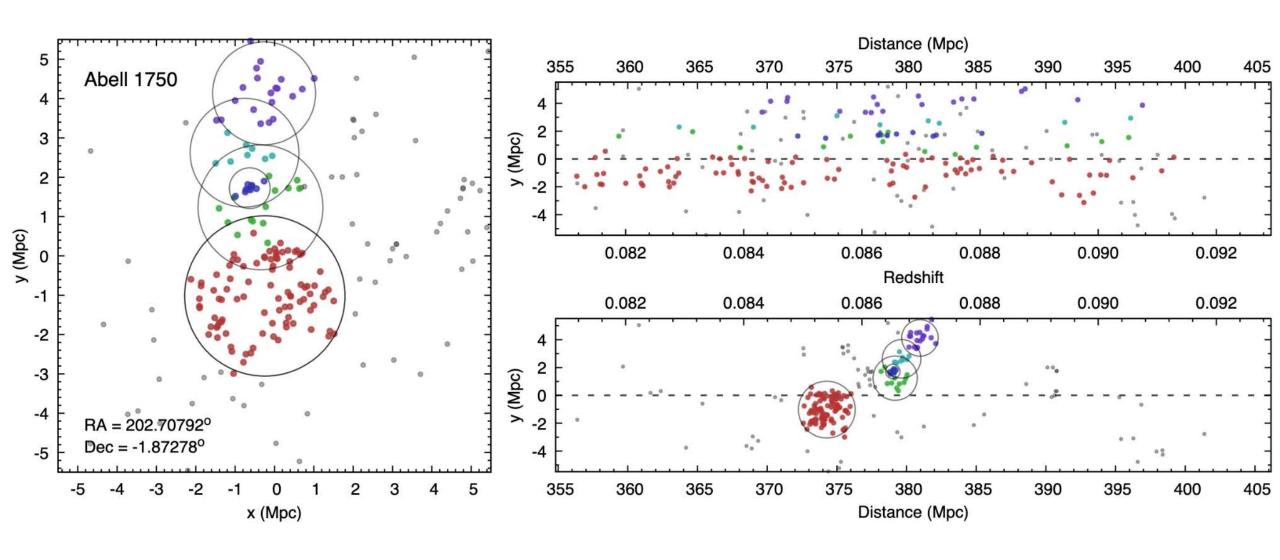
$$\begin{array}{lcl} d_{\rm gal} & = & d_{\rm group} + \left(d_{\rm gal}^{\star} - d_{\rm group} \right) \frac{d_{LL}(z)}{|v_1 - v_2|/H_0}, \\ & & \text{if } |v_1 - v_2|/H_0 > d_{LL}(z). \end{array}$$

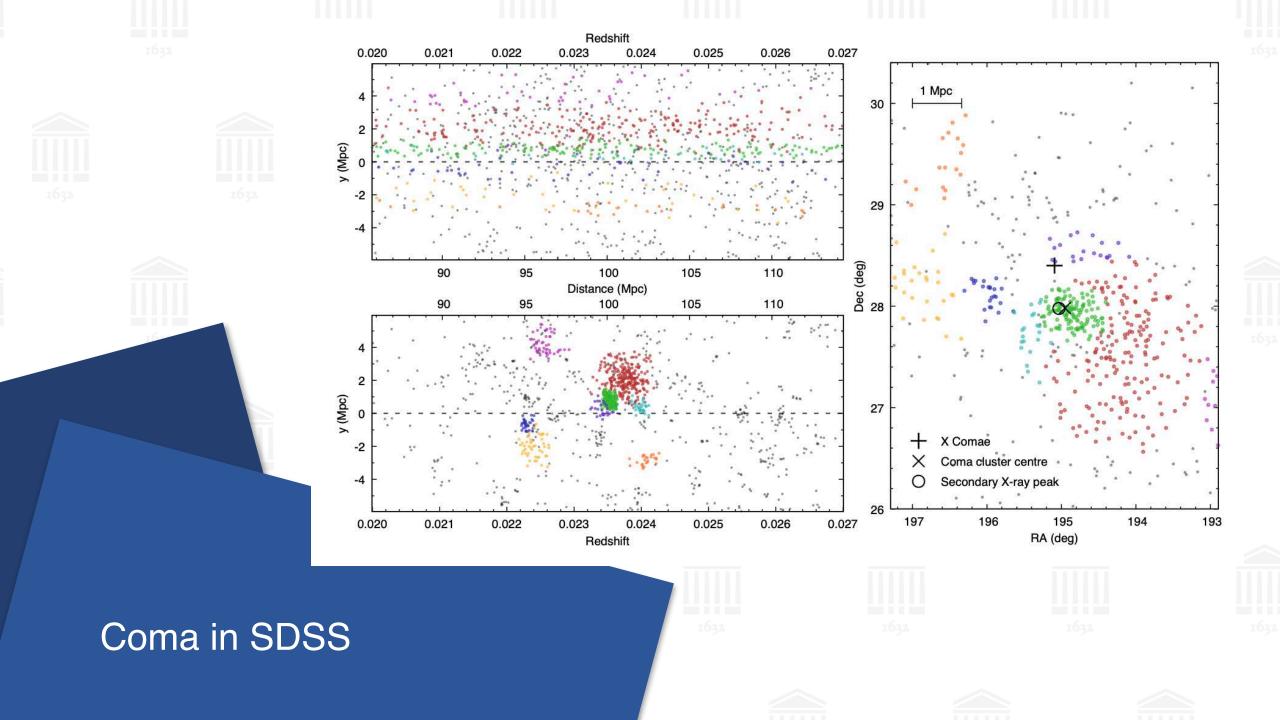






Correction for the redshift space distortions





Measuring group properties - centre

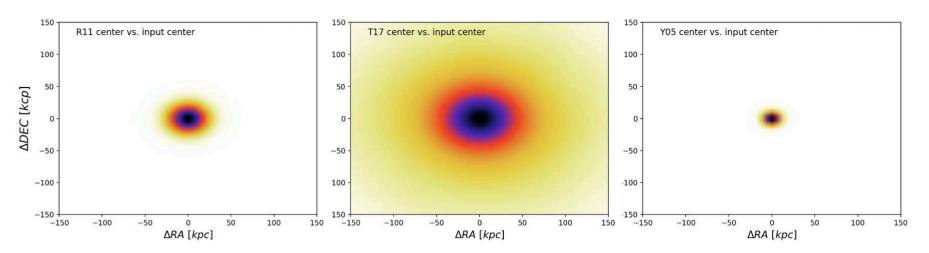


Fig. 6. The figure shows the difference in ΔRA and ΔDEC , estimated in kpc, between the center of the detected optical group and the center of the input halo (left panel), the coordinates of the eSASS X-ray detection and the center of the input halo (central panel), and the center of the detected optical group and of the eSASS X-ray detection.

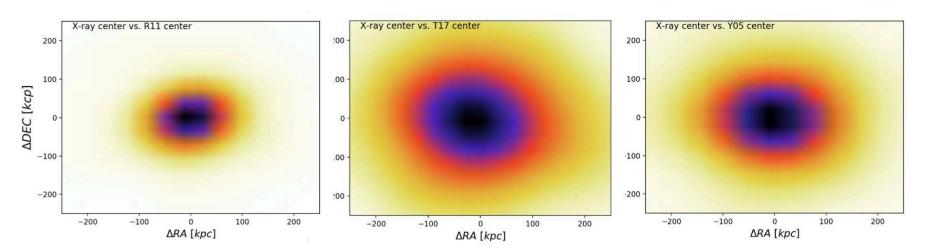
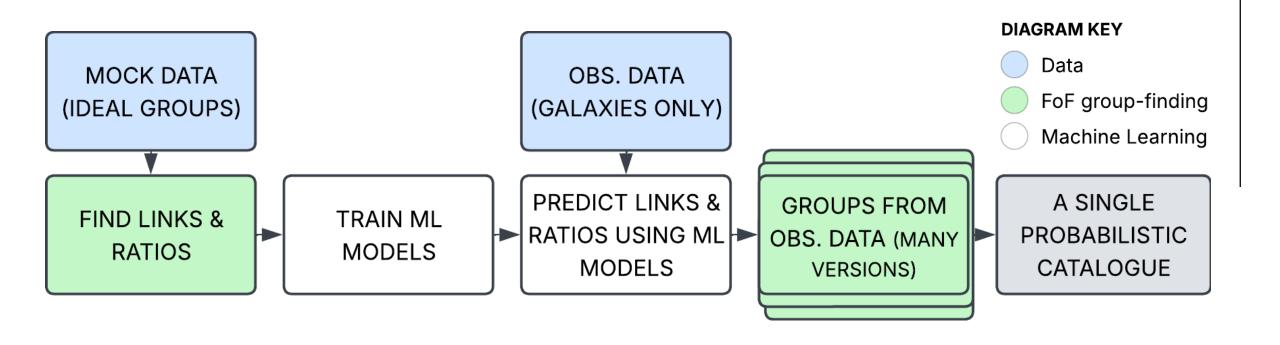


Fig. 7. The figure shows the difference in ΔRA and ΔDEC , estimated in kpc, between the center of the detected optical group and the center of the input halo (left panel), the coordinates of the eSASS X-ray detection and the center of the input halo (central panel), and the center of the detected optical group and of the eSASS X-ray detection.

The Current Group-Finder Pipeline



Two components: finding D_{\perp} , R and training ML model

Tartu Group-Finder

<u>Improvements</u>

Merged groups: refinement part of FoF

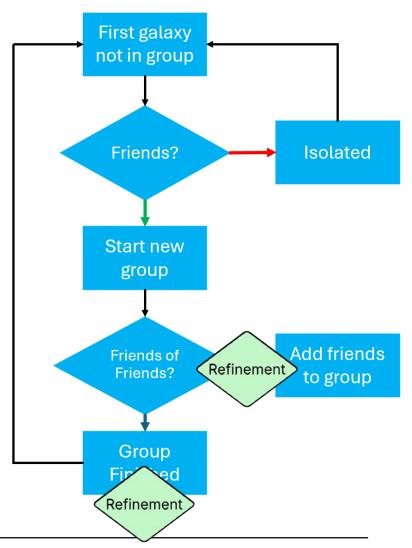
Accuracy: unique D₁, R for all galaxies

Niche: ML component

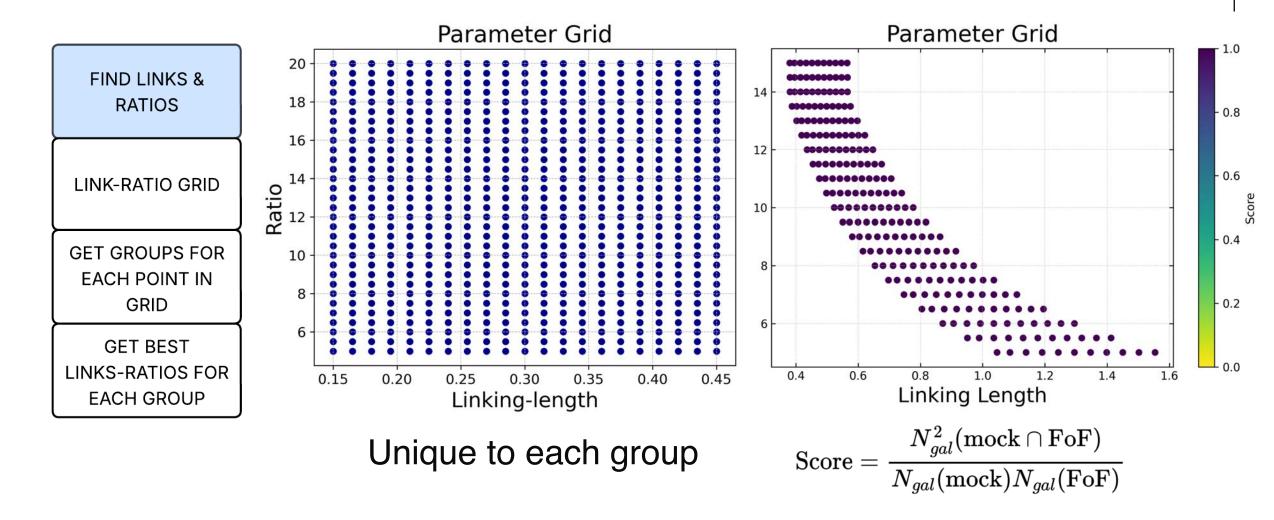
Universality: optimisable for *almost* any

dataset

Output: probabilistic catalogue.. TBD



Finding D₁, R for Mock Groups



ML Model

Training (XGBRegressor)

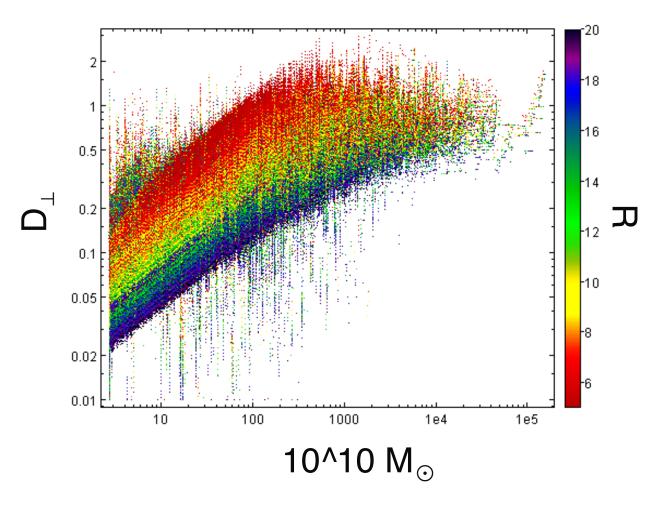
Inputs: Group mass, Ngal, Z, mag

Outputs: D₁, R

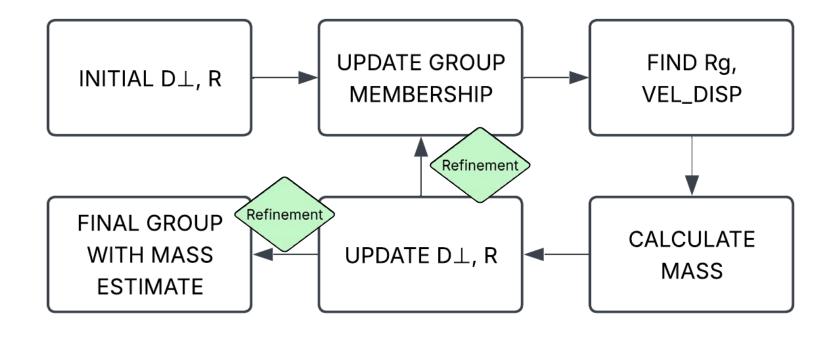
Predicting

 D_{\perp} , R for a wide range of possible

Ngal & group masses



Mass Estimation Inside FoF



$$M_{tot} = 2.325 \times 10^{12} \frac{R_g}{\text{Mpc}} \left(\frac{\sigma_v}{100 \text{ km} s^{-1}} \right)^2 M_{\odot}$$

Slide credit: Trystan Lambert

The WAVES-TWG4 Open Invitational



FRAKENSTEIN

- The perfect group finder
- Highly optimized for WAVES and consequently for 4HS too.
- Massive benefit to the community too.

JOIN US!!

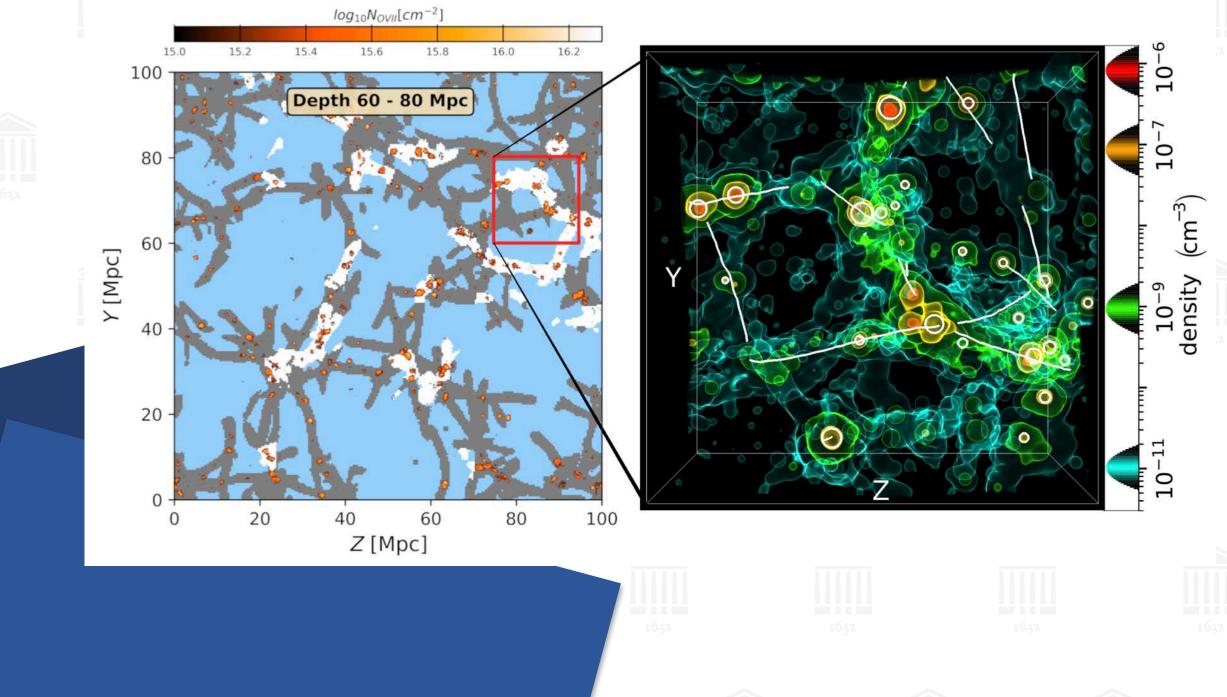


Filaments in the Cosmic Web



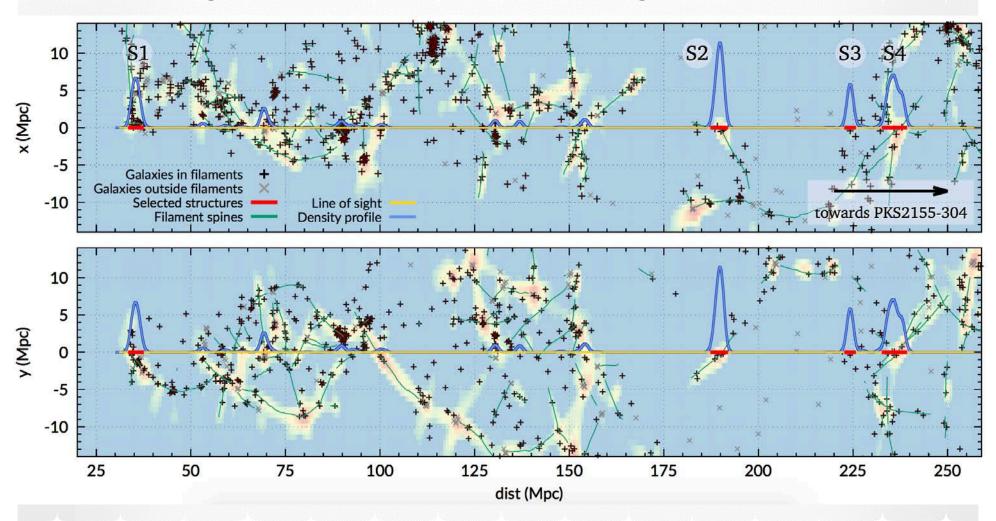


Funded by the European Union





Hunting for WHIM (warm hot intergalactic medium)

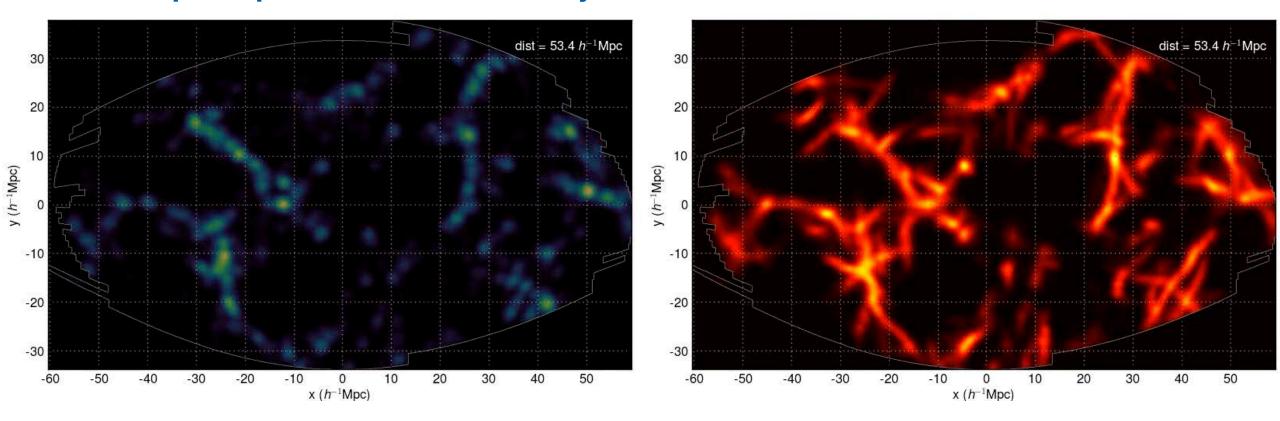


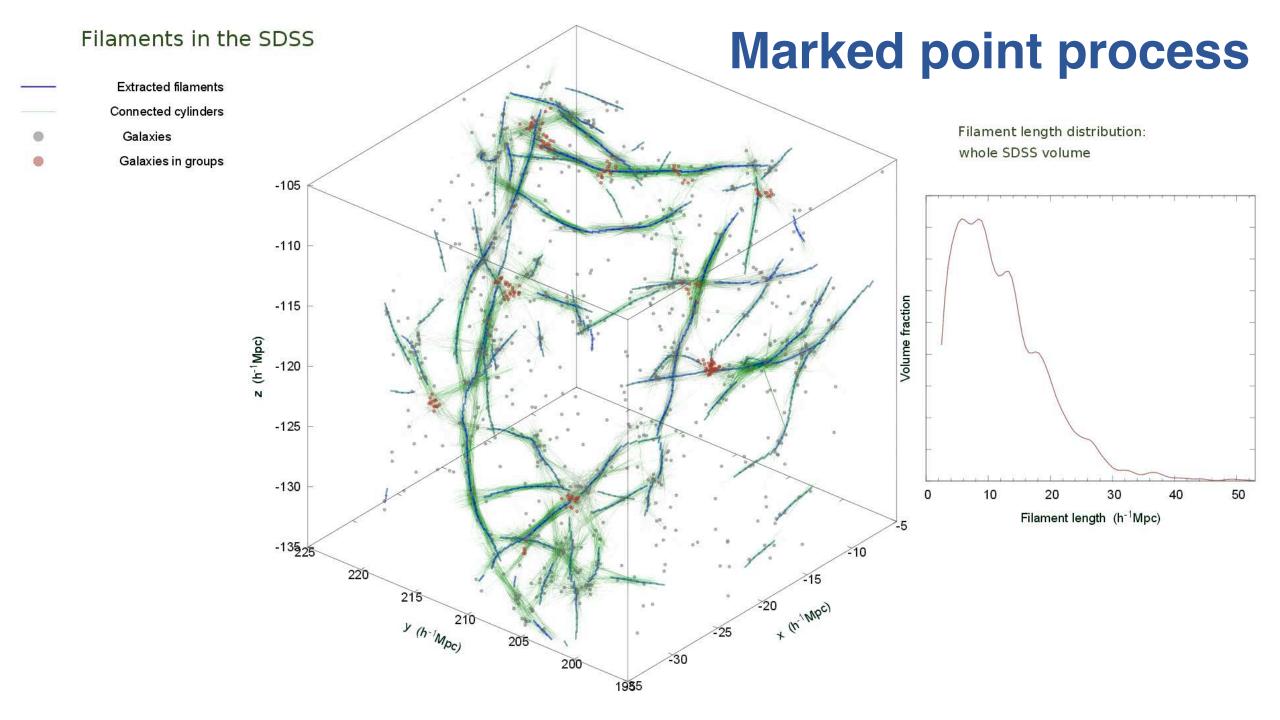
Why do we care about the cosmic web?



Galaxy filaments

Marked point process for filamentary network detection







Marked point process (Bisous model)

- → The key idea is to see the filamentary network as an object point process.
- → Cylinders are simplest objects to define a piece of filament.
- → Interactions help to form a network.
- Metropolis-Hastings algorithm (together with simulated annealing) to sample probability distribution.

Stoica et al. (2003, 2005) Stoica, Martinez, Saar (2007, 2010) Tempel et al. (2014, 2016)

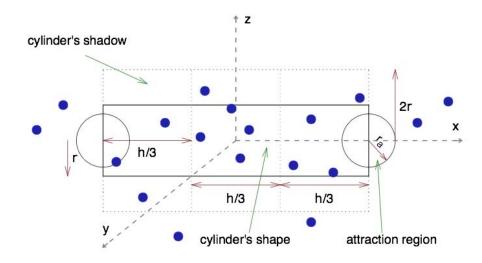


Figure 1. Two-dimensional projection of a cylinder with its shadow within a pattern of galaxies. The attraction regions are shown as spheres. The exact shape of the cylinder, it's shadow and attraction regions depend on the model.

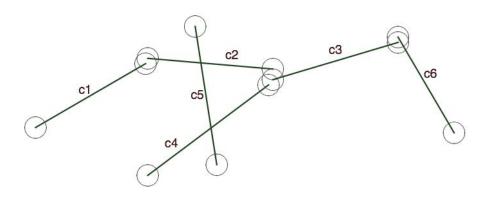


Figure 2. Two dimensional representation of cylinder configura- 71 tion: attraction regions are shown with spheres. In this configura-

Marked point process

Probability density that depends on the underlying data (position of galaxies) and the detected network (filamentary pattern)

The probability density for a marked point process based on random cylinders can be written

$$p(\boldsymbol{y}|\theta) = \frac{\exp\left[-U(\boldsymbol{y}|\theta)\right]}{\alpha} \tag{4}$$

where α is the normalising constant, θ is the vector of the model parameters and $U(y|\theta)$ is the energy function of the system. Here, y is the configuration of cylinders.

Bisous model (Candy model)

Following these two ideas the energy function given by (4) can be specified as:

$$U(\boldsymbol{y}|\theta) = U_{\rm d}(\boldsymbol{y}|\theta) + U_{\rm i}(\boldsymbol{y}|\theta), \tag{5}$$

where $U_{\rm d}(\boldsymbol{y}|\boldsymbol{\theta})$ is the data energy (see Sect. 3.4) and $U_{\rm i}(\boldsymbol{y}|\boldsymbol{\theta})$ is the interaction energy (see Sect. 3.5) associated to the first and second assumptions above, respectively. In fact, it is perfectly reasonable to think that the data energy is the reason that the cylinders in the galaxy field are positioned just so, and that the interaction energy is the main factor which causes the cylinders to form filamentary patterns.



Marked point process

Metropolis-Hastings algorithm to sample from probability density:

$$p(oldsymbol{y}| heta) = rac{\exp\left[-U(oldsymbol{y}| heta)
ight]}{lpha}$$

- birth (uniform, connected)
- death
- o change

$$\min\left\{1, \frac{p_d}{p_b} \frac{d(\mathbf{y} \cup \{\zeta\}, \zeta)}{b(\mathbf{y}, \zeta)} \frac{p_n(\mathbf{y} \cup \{\zeta\})}{p_n(\mathbf{y})}\right\}$$

$$b(\mathbf{y},\zeta) = \frac{p_1}{v(K)} + p_2 b_a(\mathbf{y},\zeta)$$

Simulated annealing:

$$p_n(\mathbf{y}) \propto [p(\mathbf{y})]^{\frac{1}{T_n}}$$

$$T_n = \frac{1}{\log(n+1)}$$

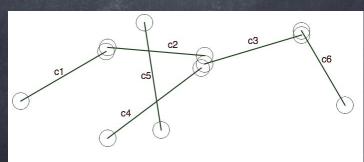


Figure 2. Two dimensional representation of cylinder configuration: attraction regions are shown with spheres. In this configu-

Bisous model

Data energy:

$$U_{\mathbf{d}}(\mathbf{x}|\theta) = -\sum_{x \in \mathbf{x}} \left[\log(p_{vu}(x)p_{vh}(x)) - \sigma^2(x) \right], \qquad (27)$$

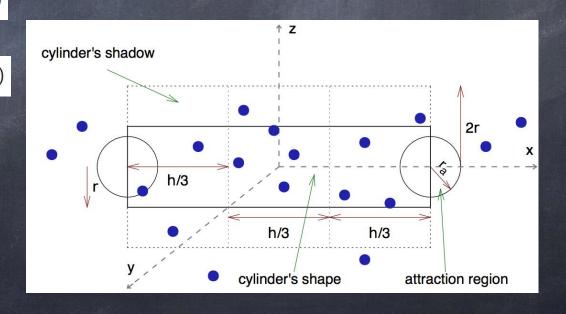
Hypothesis testing to test the "uniformity" of a filament and to test the "locally high density" in a filament.

$$p_{vu} = \mathbf{P}[X|X + \tilde{X}, p(\rho_u)] \leqslant \alpha_u, \tag{21}$$

$$p_{vh} = \mathbf{P}[X|X + \tilde{X}, p(\rho_h)] \leqslant 1 - \alpha_h. \tag{24}$$

Cylinder concentration:

$$\sigma^2 = \frac{1}{n-2} \sum_{j=1}^n d_j^2, \tag{25}$$

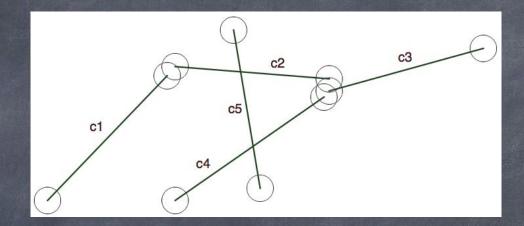




Bisous model

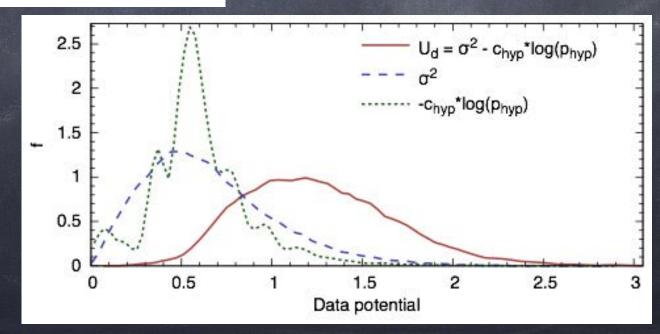
Interaction energy:

Repulsive cylinders, 0,1,2-connected cylinders



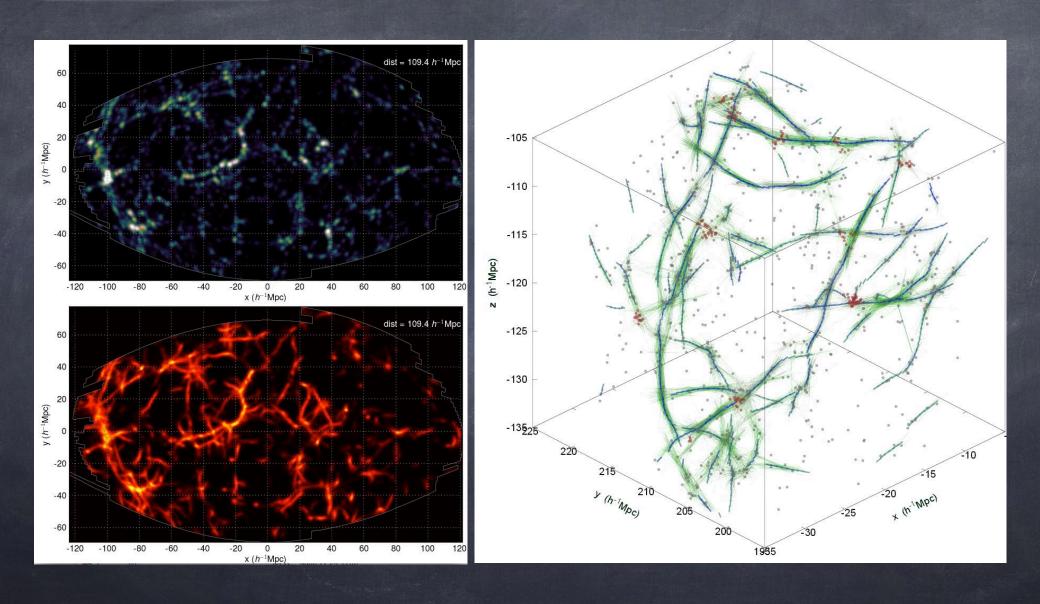
$$U_i(\boldsymbol{y}|\theta) = -n_k(\boldsymbol{y})\log \gamma_k - \sum_{2=0}^2 n_s(\boldsymbol{y})\log \gamma_s,$$
 (29)

Data energy:





Results: detected filaments





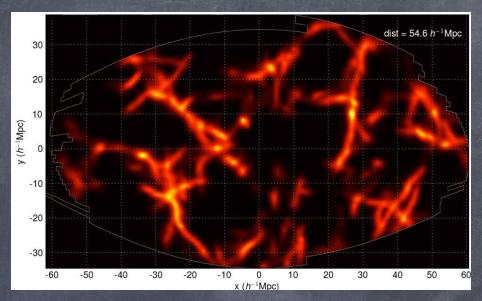
Extracting single filaments

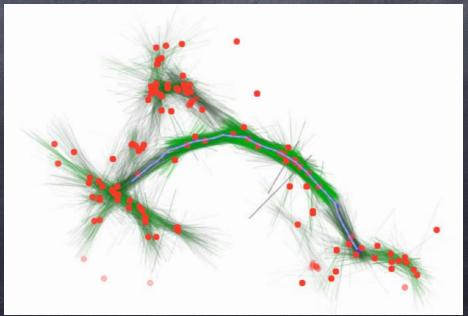
- Set of simulations (50 simulations):100000x200000 moves!

1

- Density field of filaments
- Orientation field of filaments

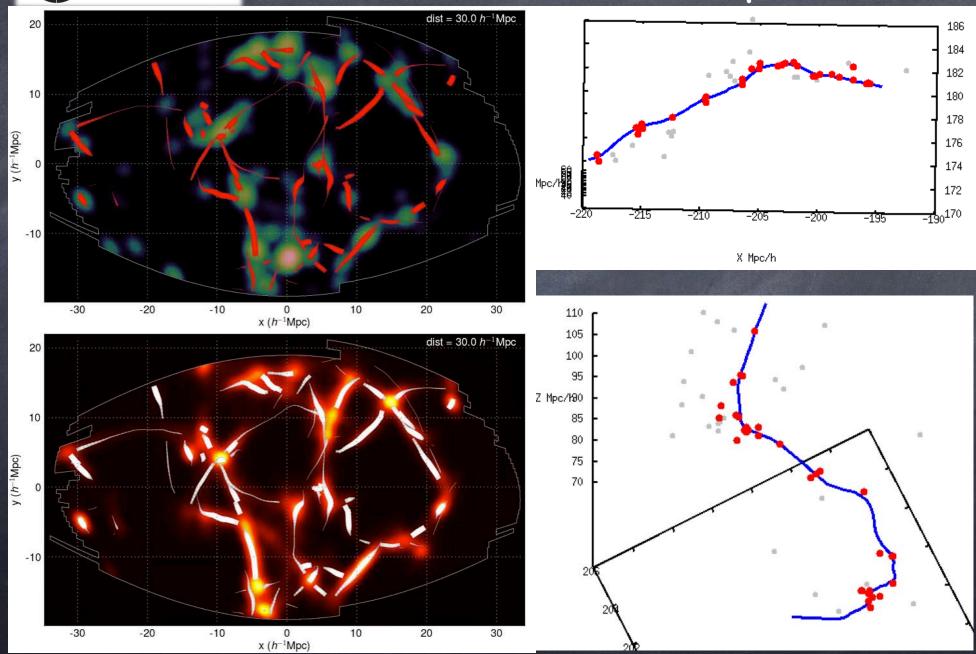
Single filaments





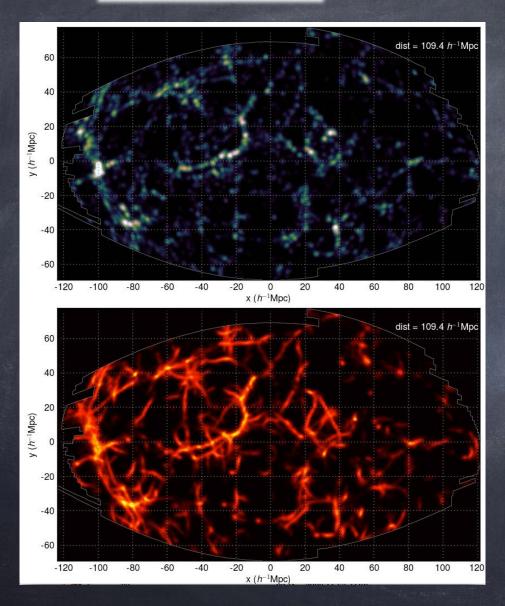


Detected filament spines





Detected filamentary pattern

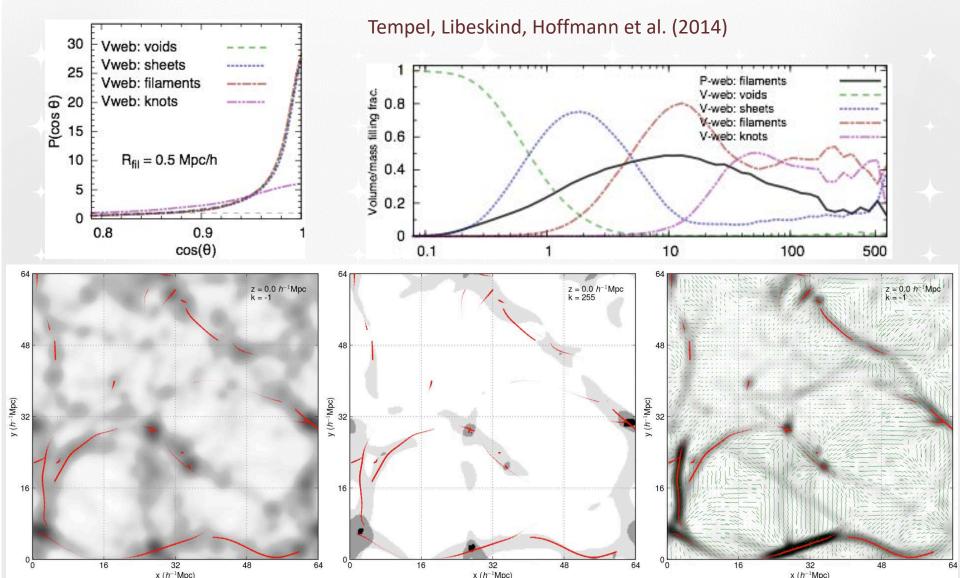




Juhan Liivamägi

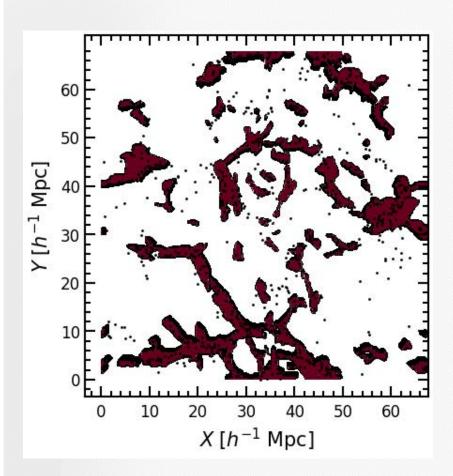
Toni Tuominen

Orientation of cosmic web filaments with respect to the underlying velocity field

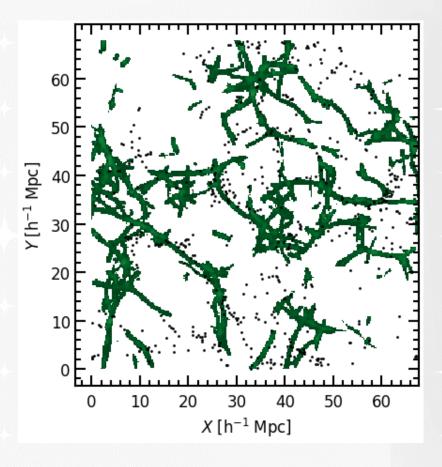


Filaments in Eagle simulation: Bisous vs Nexus

Nexus: Dark Matter

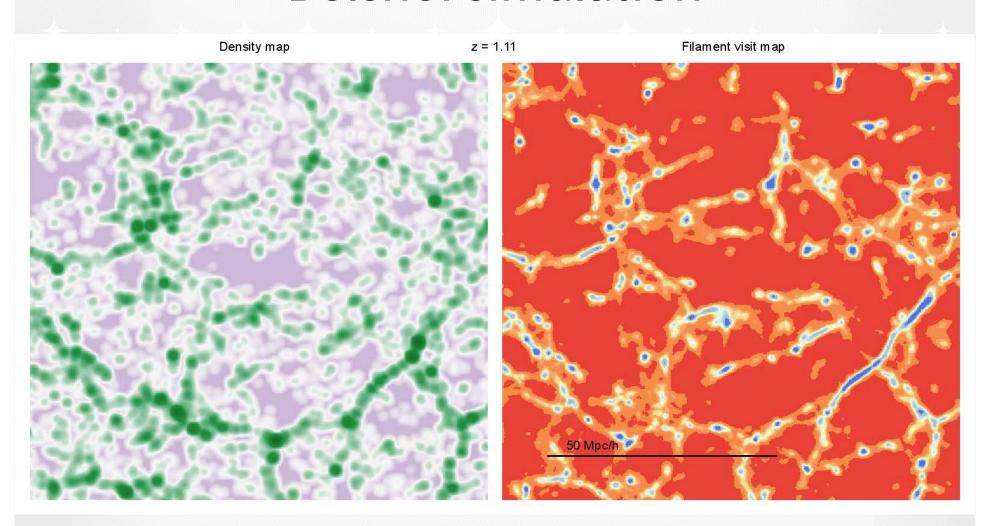


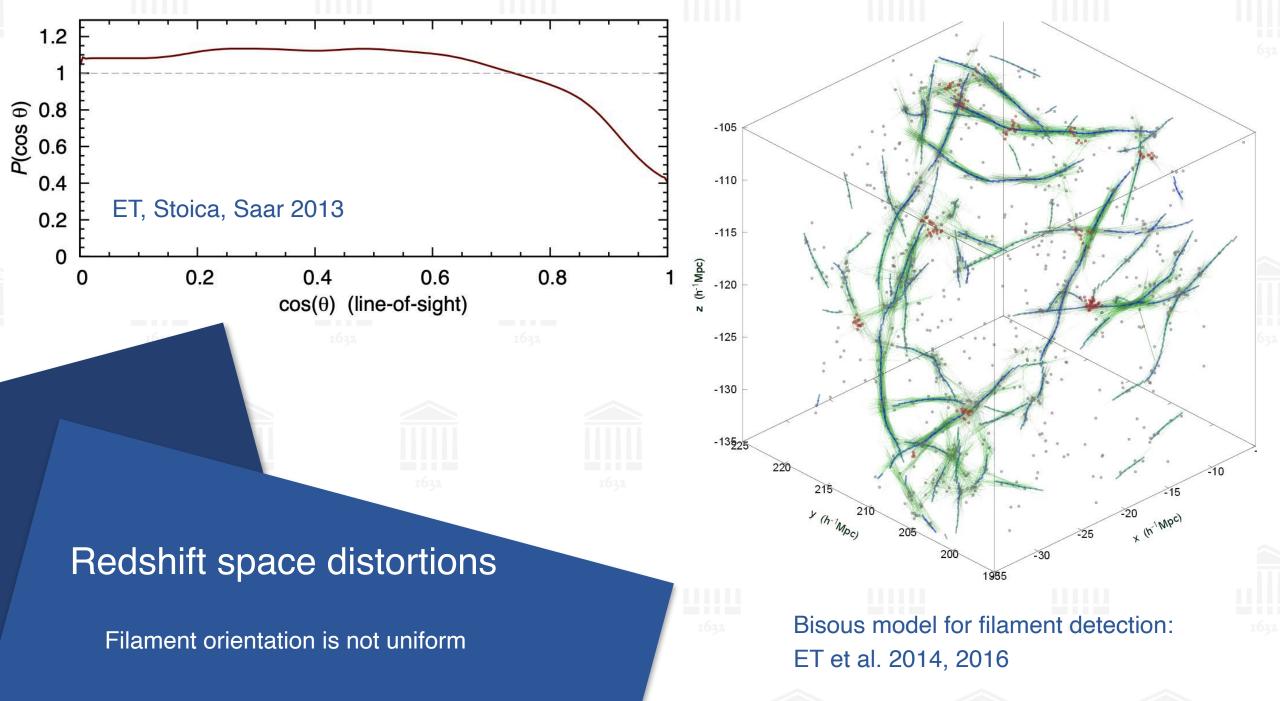
Bisous: galaxies





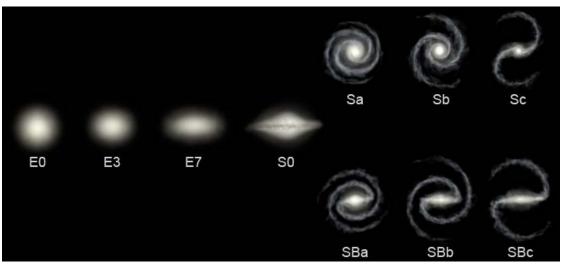
Bolshoi simulation



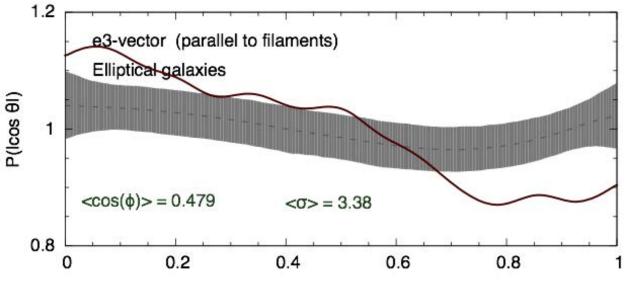




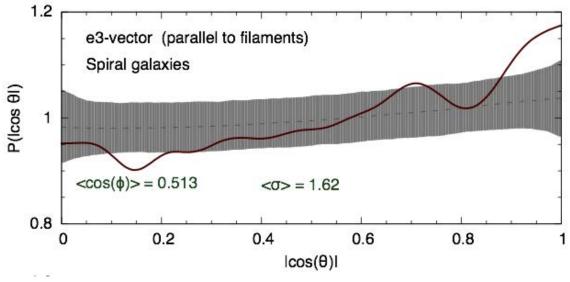
Galaxy filament alignment



Ellipticals



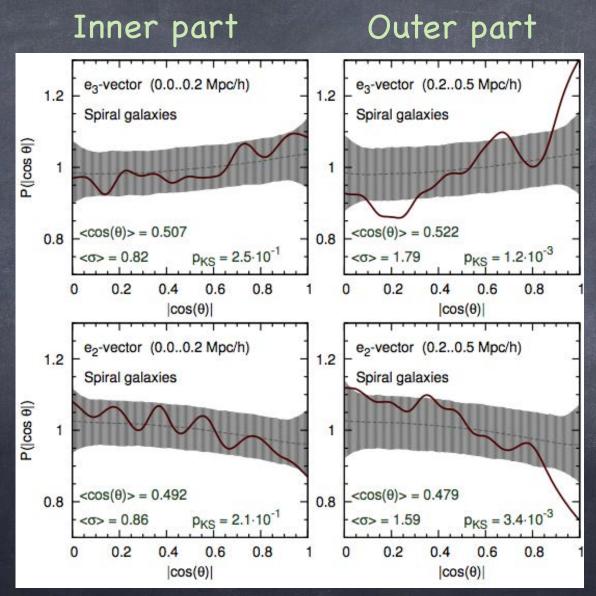
Spirals



Tempel et al. (2013)



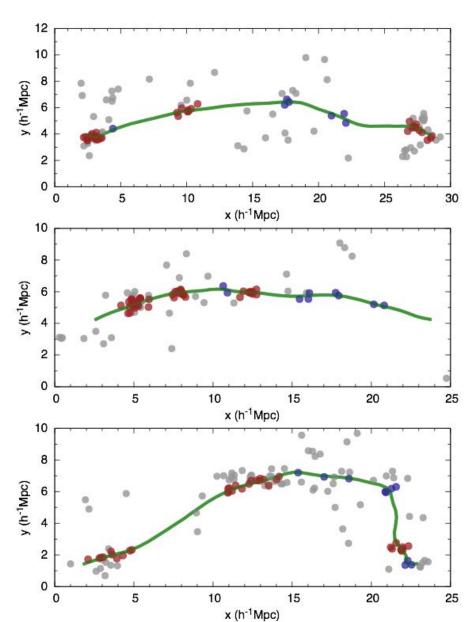
Filaments and galaxy formation



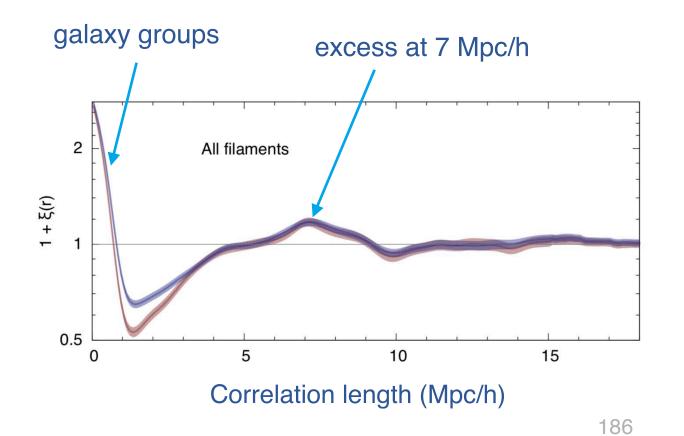


Galaxy filaments as pearl necklaces

Tempel et al. (2014)

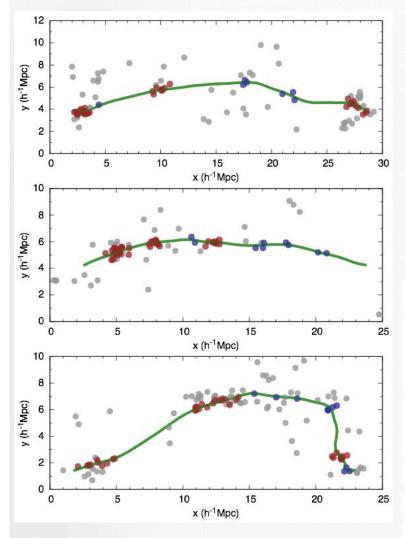


Pair correlation function along the filaments





Data and methods



Pair correlation function:

$$\widehat{\xi}(r) = 1 + \frac{DD(r)}{RR(r)} - 2\frac{DR(r)}{RR(r)},$$

Rayleigh Z-squared statistics:

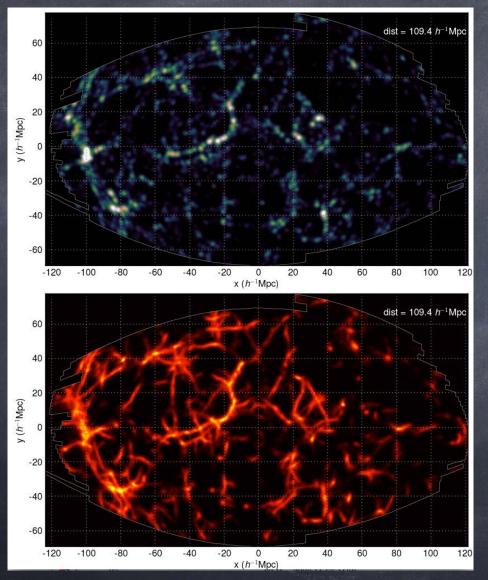
The algorithm works as following. For each filament, we produce a periodogram using the Z_1^2 (Rayleigh statistics),

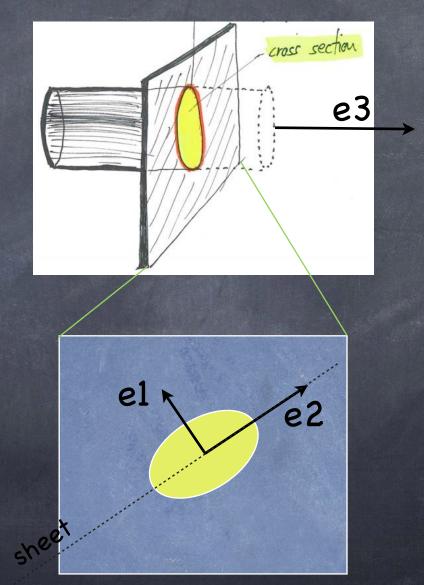
$$Z_1^2 = \frac{2}{N} \left[\left(\sum_{j=1}^N \cos \phi_j \right)^2 + \left(\sum_{j=1}^N \sin \phi_j \right)^2 \right], \tag{4}$$

where N is the number of galaxies in a filament and $\phi_j = 2\pi l_j/d$ is the phase value for a galaxy j for a fixed period d; l_j is a galaxy j distance along the filament spine from the beginning of the filament.



Detected filamentary pattern: sheet orientation





Galaxy pairs align with galactic filaments

Tempel & Tamm (2015)

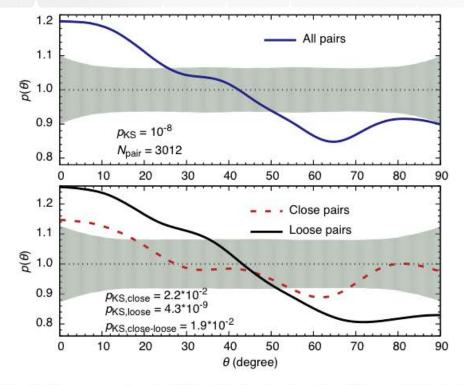
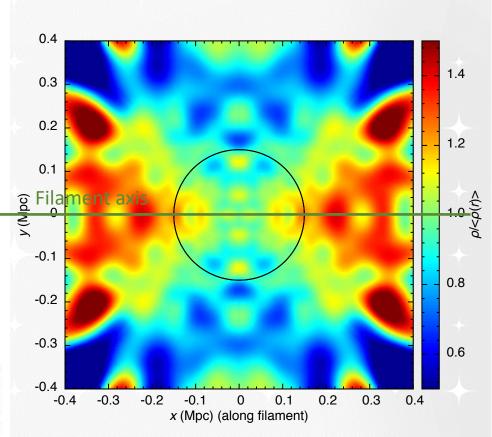
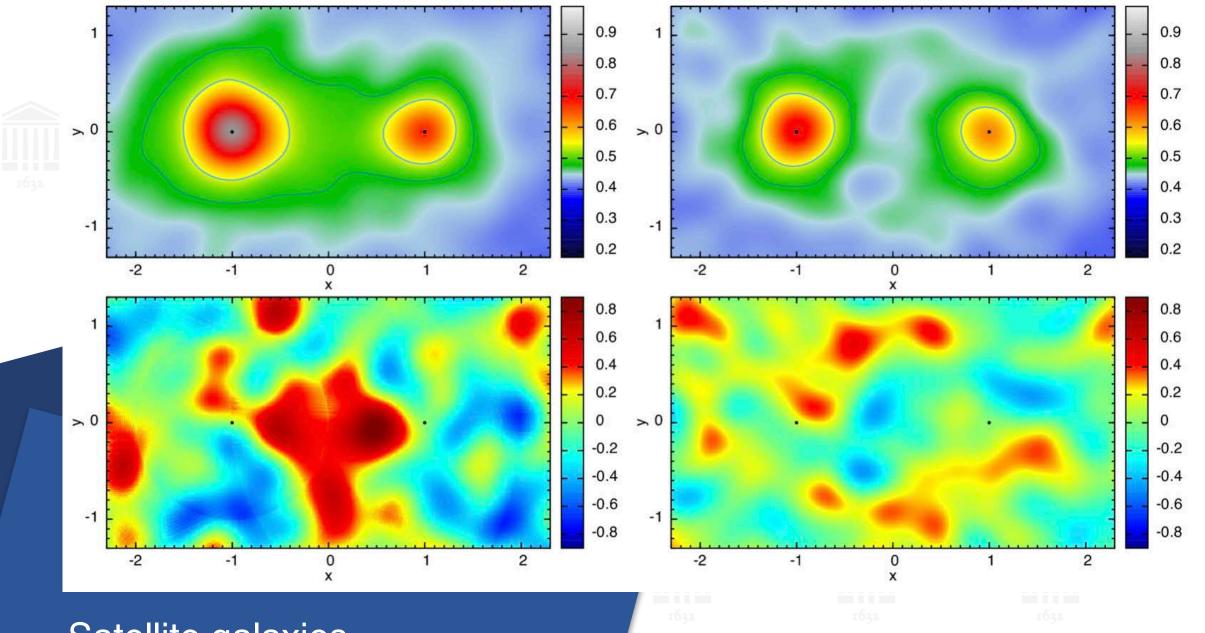


Fig. 2. *Upper panel*: probability distribution function (blue solid line) of the projected (in the plane of the sky) angles between galaxy pairs and their host filaments. The KS-test value that the sample is drawn from a uniform distribution is 10^{-8} . The filled area shows the 95% confidence region for a randomised distribution of 3012 pairs. *Lower panel*: the same as in the upper panel for two equal-size subsamples: close pairs $(d_{\text{sep}} < 0.3 \text{ Mpc}; \text{ red dashed line})$ and loose pairs $(d_{\text{sep}} > 0.3 \text{ Mpc}; \text{ black solid line})$.

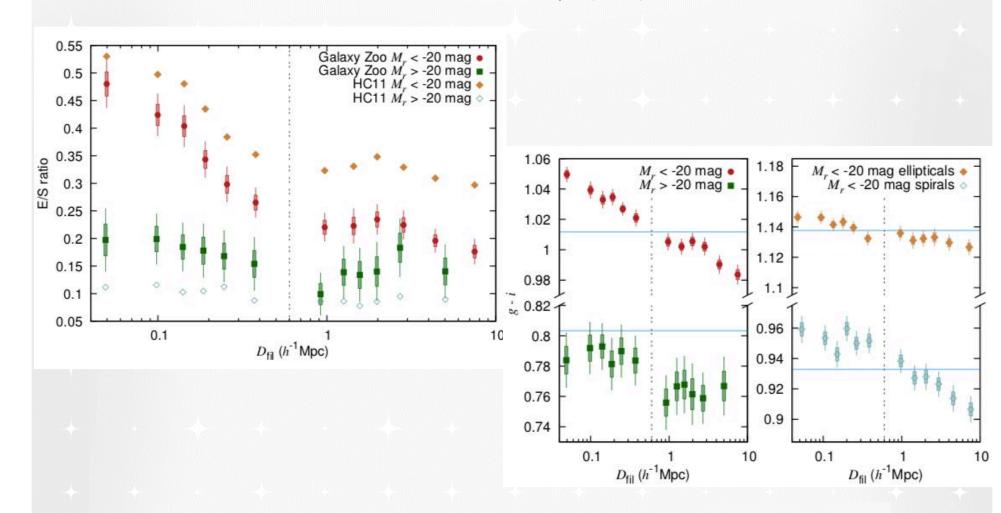




Satellite galaxies

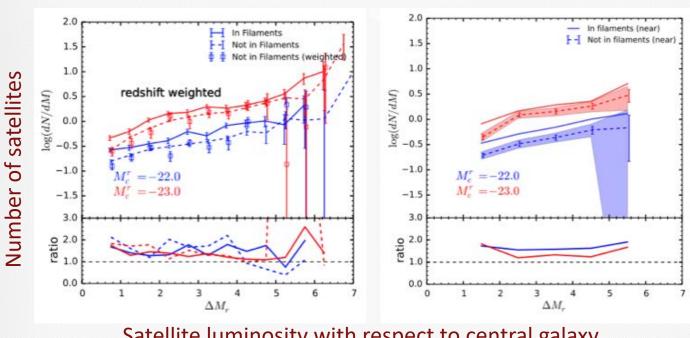
Galaxy properties in filament environment

Kuutma, Tamm & Tempel (2017)



Galaxies in filaments have more satellites: the influence of the cosmic web on the satellite luminosity function in the SDSS

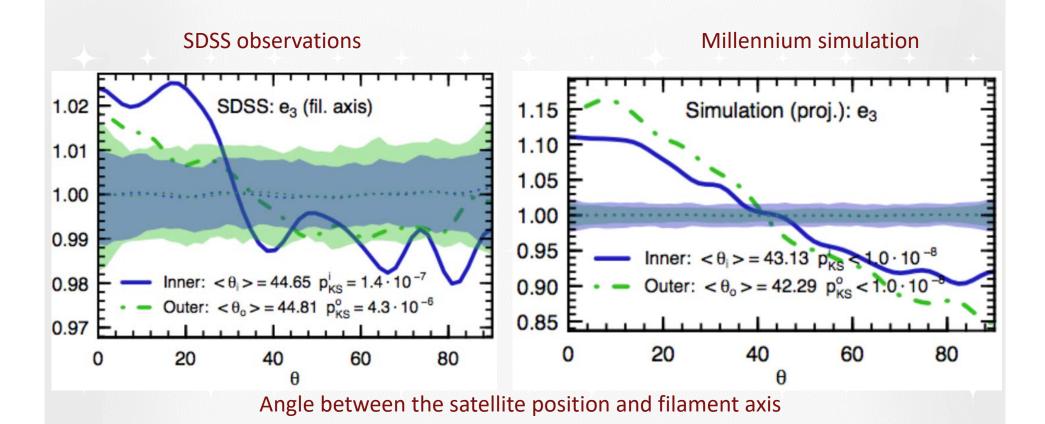
Guo, Tempel & Libeskind (2015)



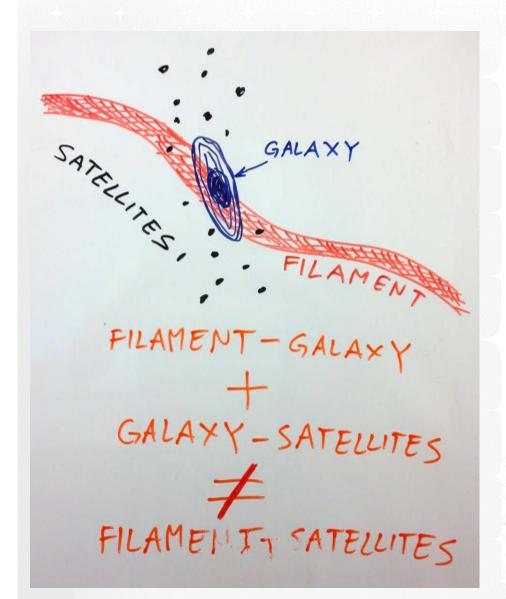
Satellite luminosity with respect to central galaxy

The alignment of satellite galaxies and cosmic filaments: observations and simulations

Tempel, Guo, Kipper, Libeskind (2015)



Intrinsics of the alignment signal



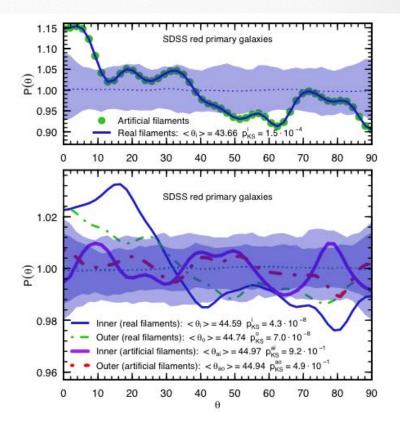
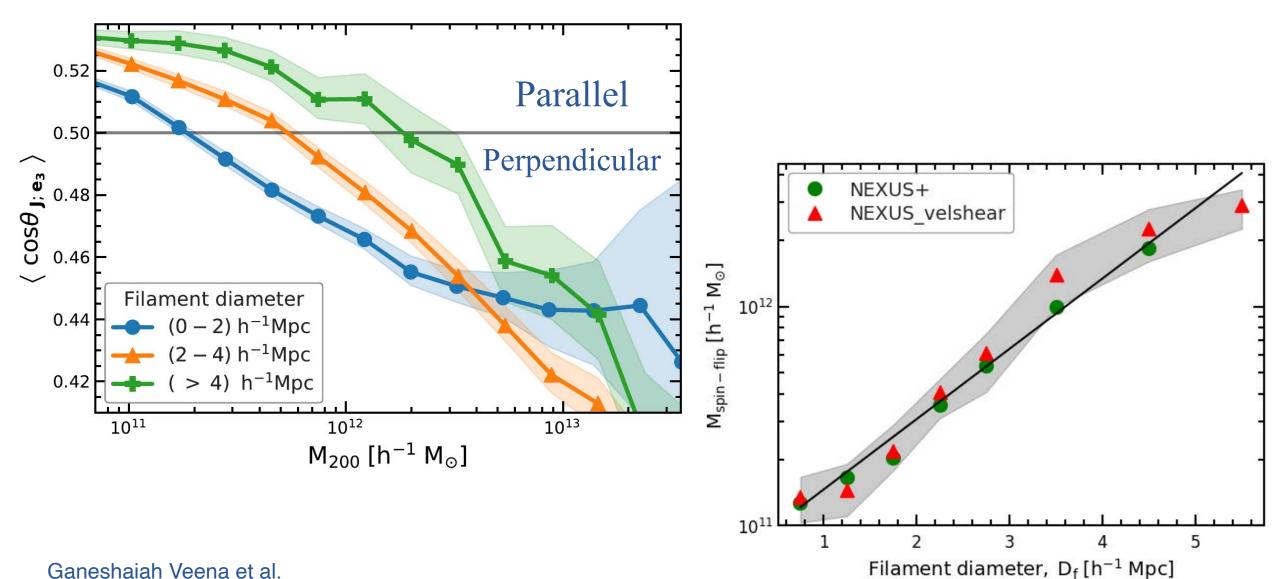


Figure 7. Test the intrinsic of the filaments between the filament axes and anisotropic distribution of satellites. *Top panel:* the alignment between real/artificial filament axes and the major axis of red primaries. *Bottom panel:* the alignments between anisotropic distribution of satellites with artificial filament axes (thick red and purple lines) and with real filament axes (thin blue and green lines).

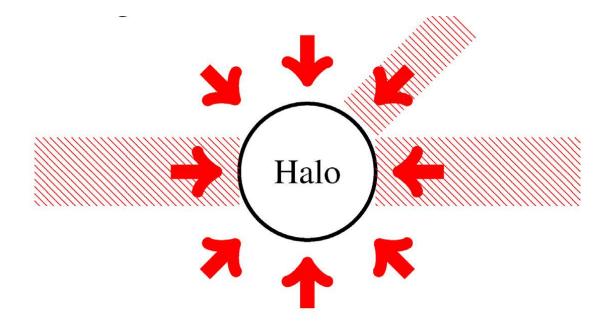


Alignment dependence on filament properties



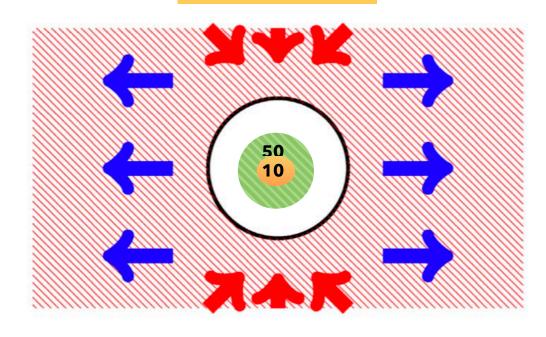
Late time accretion

ACCRETING HALO

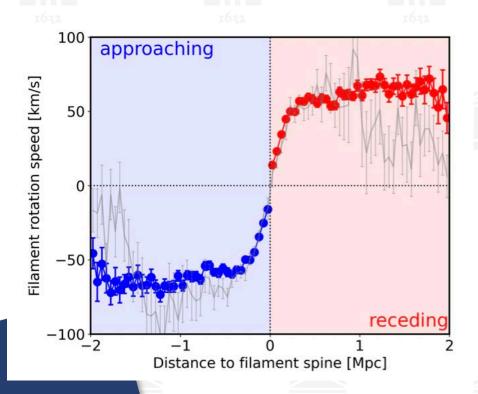


- Thin filament
- Accretion perpendicular spin

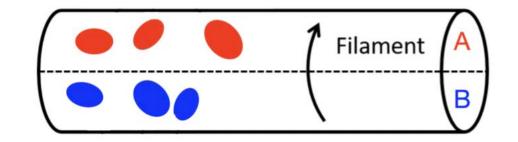
STALLED HALO

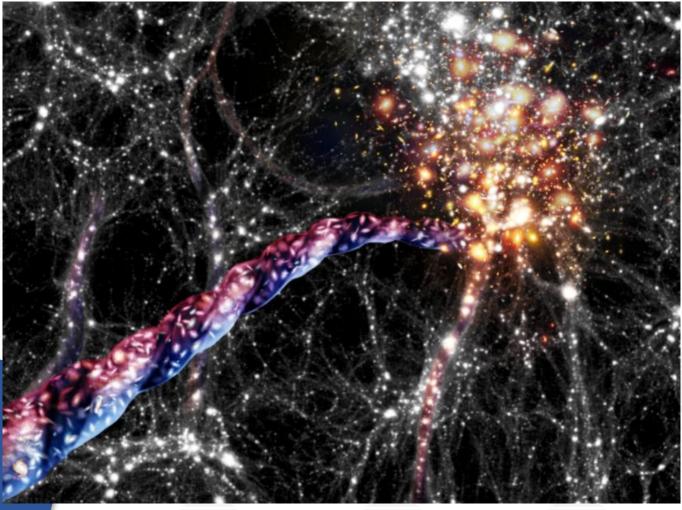


- Thick filament
- Accretion parallel spin



Rotating filaments







Science in Tartu Observatory





Funded by the European Union



4MOST - 4-metre Multi-Object Spectroscopic Telescope



Cosmic Web & Galaxies

@ Tartu Observatory



Photo-z (TOPz)
SED fitting

4MOST ProbSF

survey simulator

mFoF groups

mass estimation

BisousWeb

galaxy filaments

Weighted
Galaxy Matching

target selection
CIGALE templates
template fitting
k-correction
e-correction
galaxy properties
spec-z + photo-z

Visit Planner

4MOST scheduler

Probabilistic fibretarget assignment

Survey optimisation

Selection function

Statistical analysis

Group detection
(incl. ProbSF)
Group membership
Group masses and
mass uncertainties
ML approach
Local Environment

Filament detection

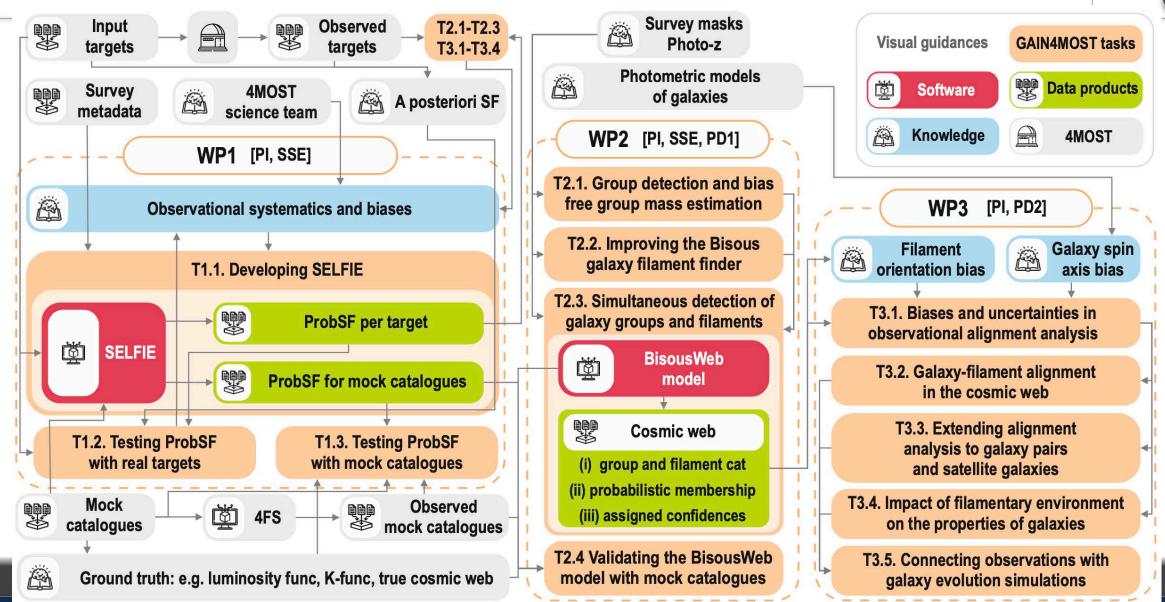
Marked point
process approach
Filament-group
connectivity
Filament properties

Cosmic Web

Scaled flux matching
Galaxy-environment
connection
Simulations vs
observations
Understanding
galaxy evolution

GAIN4MOST: Galaxy-filament Alignments IN 4MOST





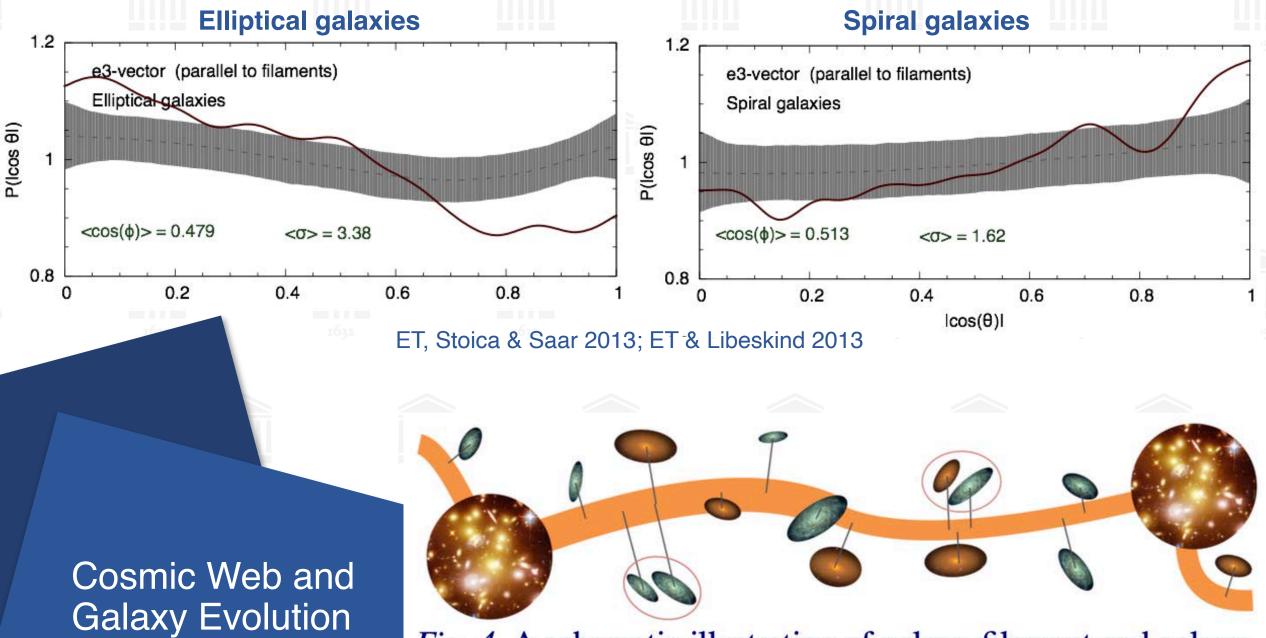
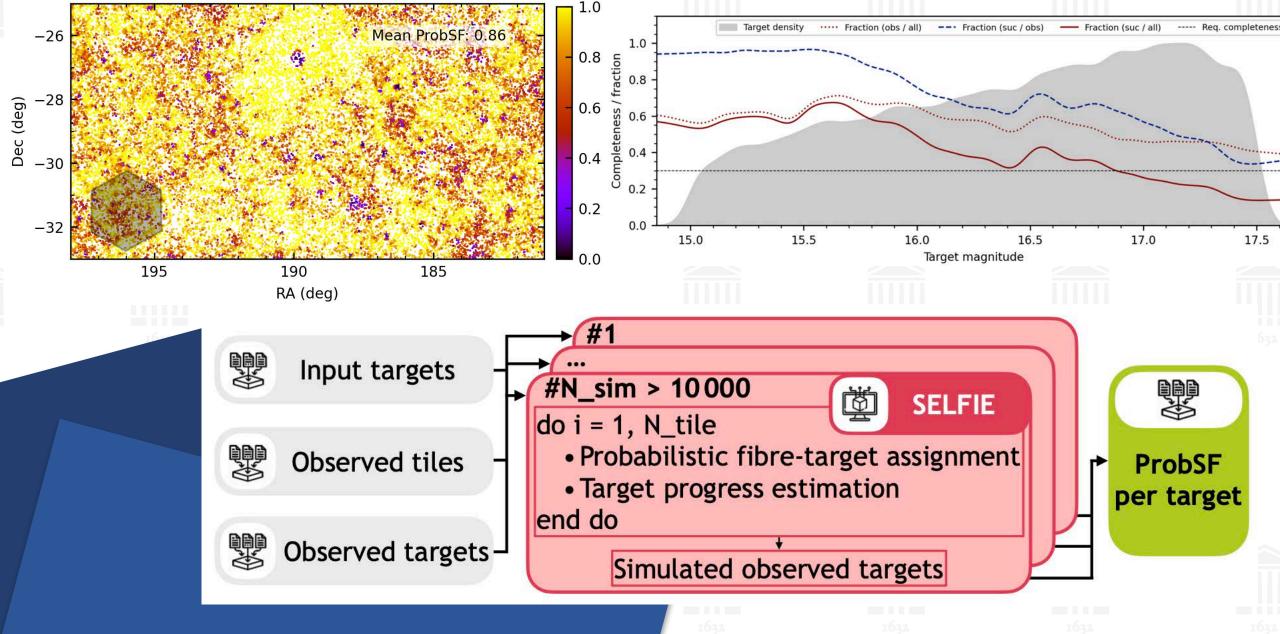


Fig. 4. A schematic illustration of galaxy-filament and galaxy-galaxy alignment in a filament that connects two clusters.



Probabilistic selection function

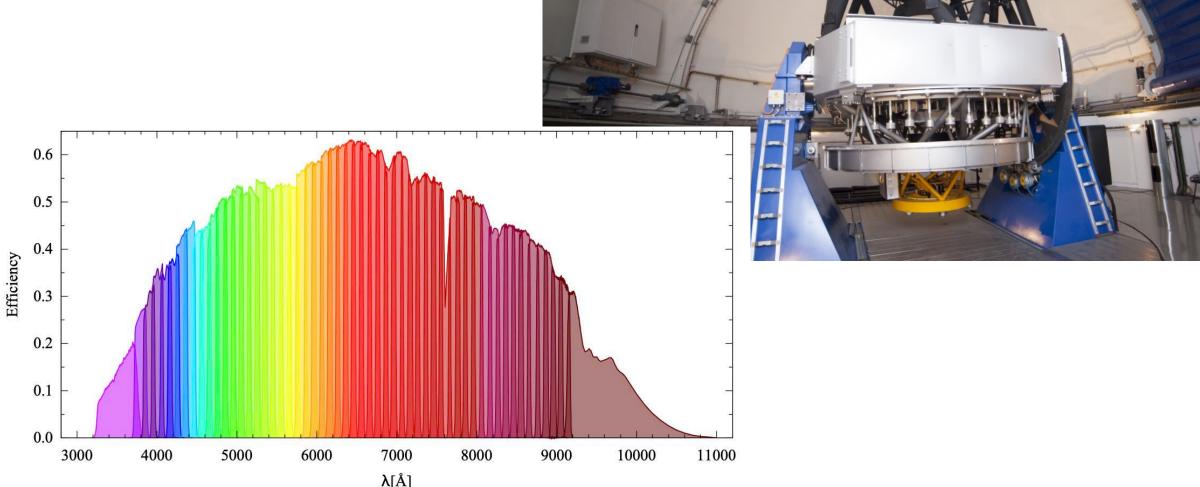
4MOST survey simulations

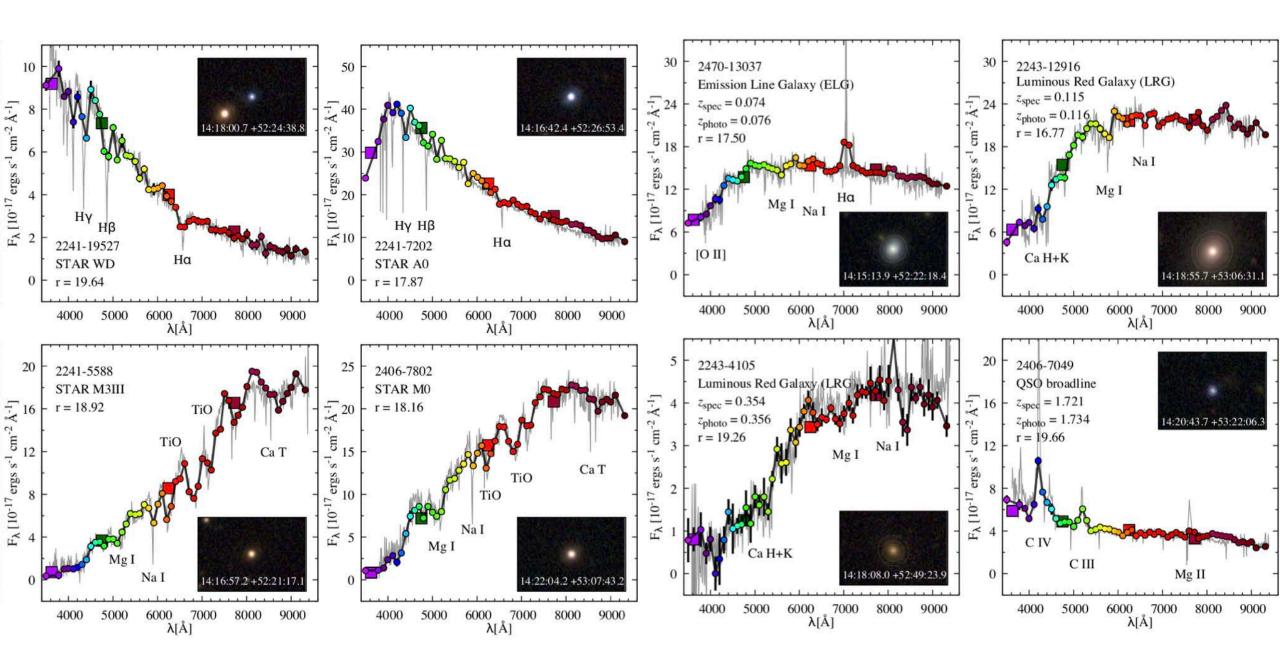
J-PAS – Javalambre Physicsof the Accelerating Universe Astrophysical Survey

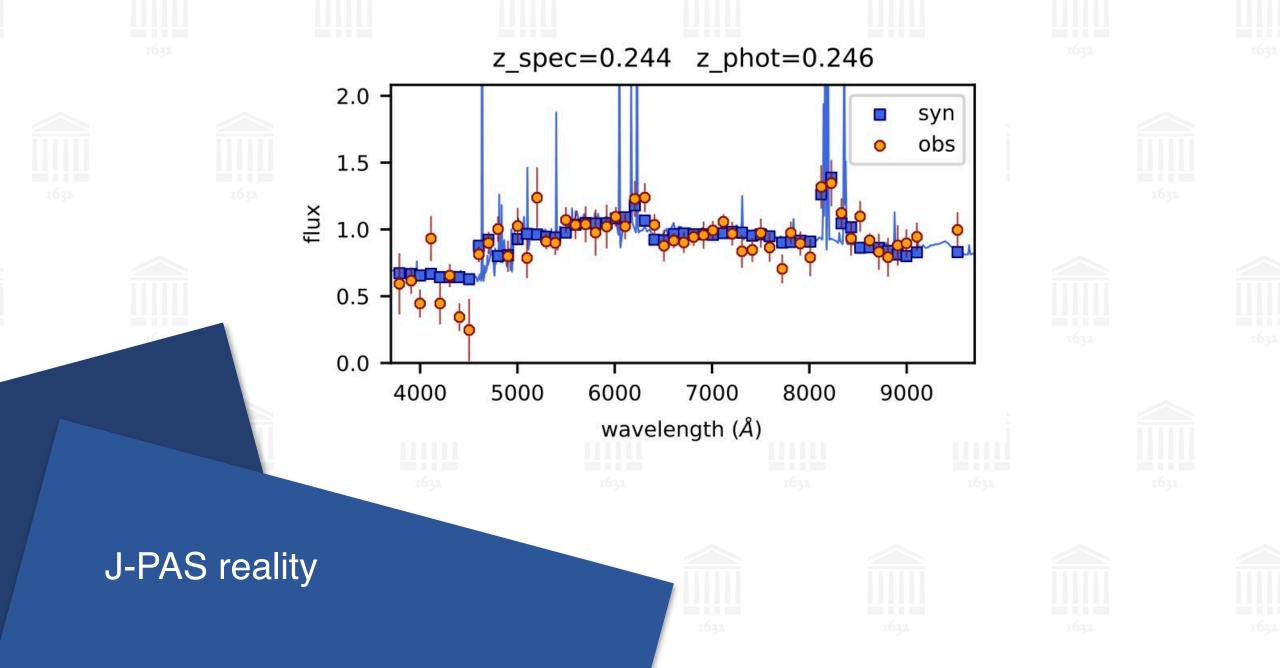


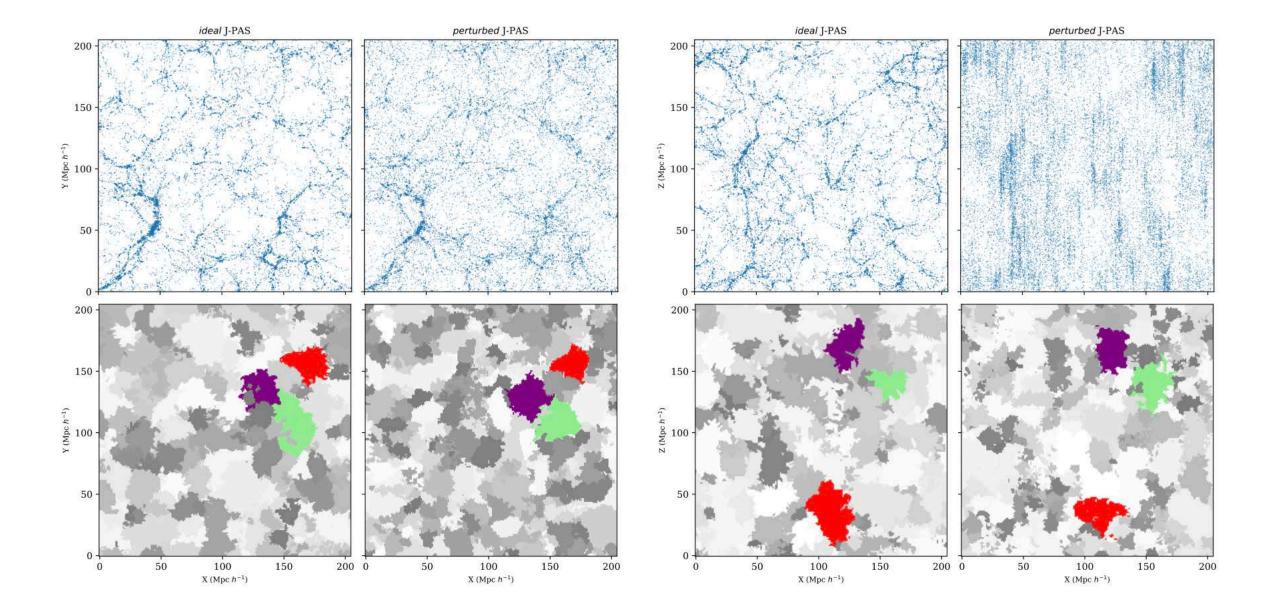
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of the Accelerating Universe Astrophysical Survey











Measuring distances - photometric redshifts





Funded by the European Union

$$p(\zeta \mid F, m_0) = \sum_{T \in \mathbf{T}} p(\zeta, T \mid F, m_0) \propto \sum_{T \in \mathbf{T}} p(\zeta, T \mid m_0) p(F \mid \zeta, T), \quad (1)$$

0.1

0.2

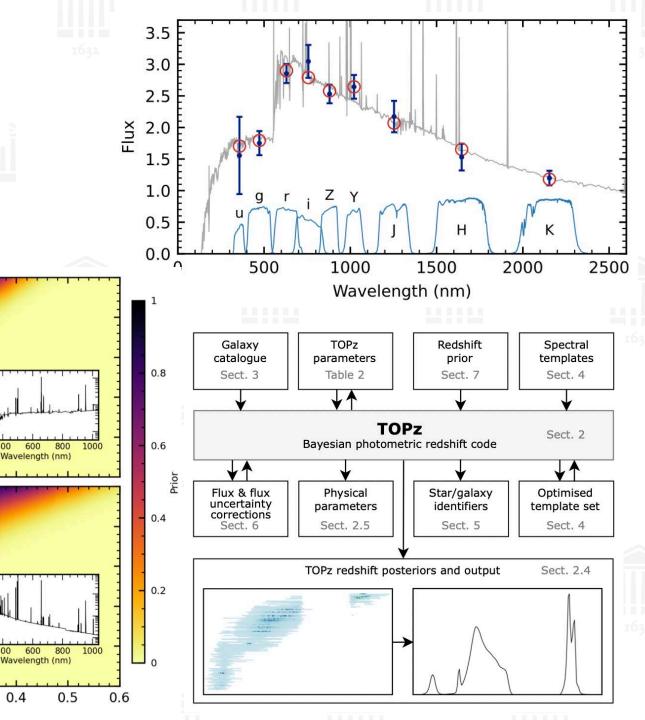
Magnitude

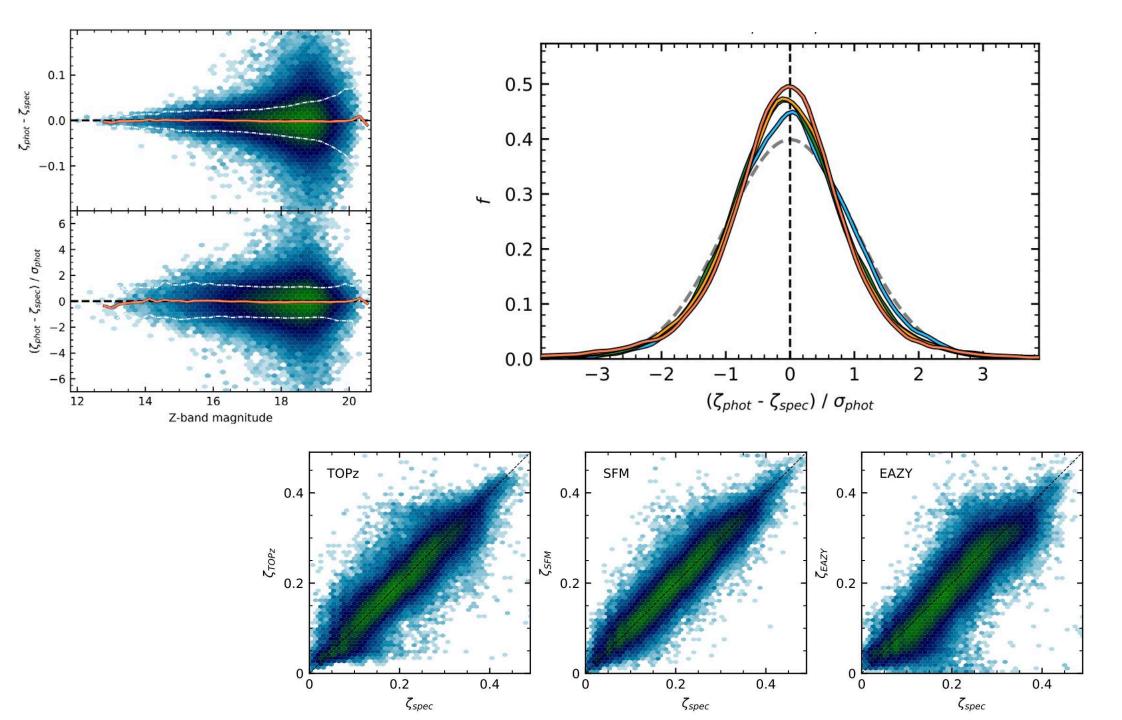
0.4

0.3

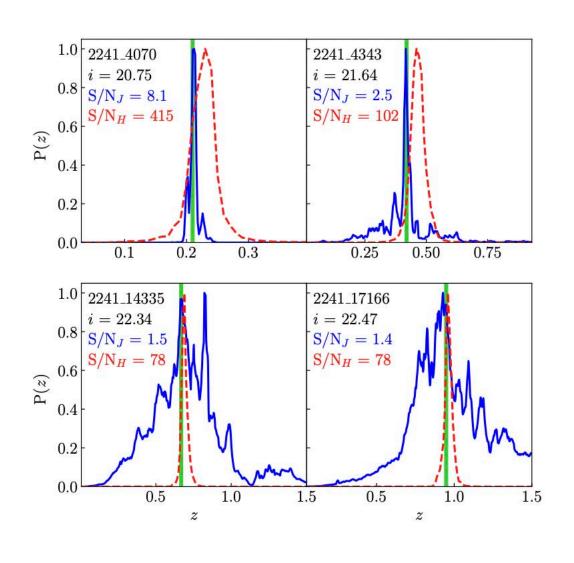
$$p(F \mid \zeta, T) \propto \frac{1}{\sqrt{F_{\mathrm{TT}}}} \exp\left[-\frac{\chi^2(\zeta, T, a_m)}{2}\right],$$

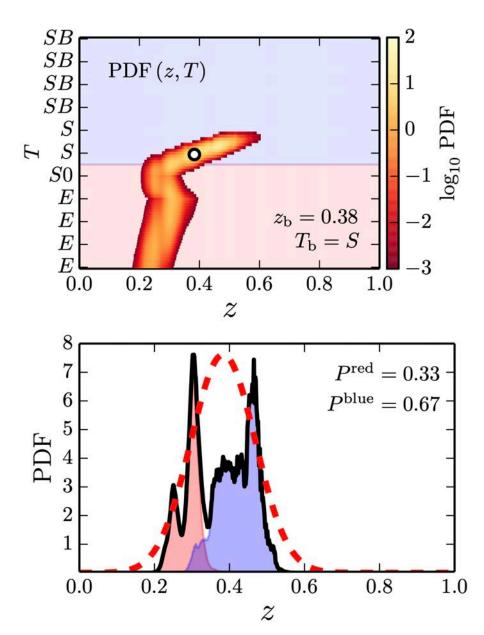
$$F_{T\alpha} = \frac{\int f_{T,\zeta}(\lambda) W_{\alpha}(\lambda) \, \mathrm{d}\lambda}{\int W_{\alpha}(\lambda) \, \mathrm{d}\lambda},$$

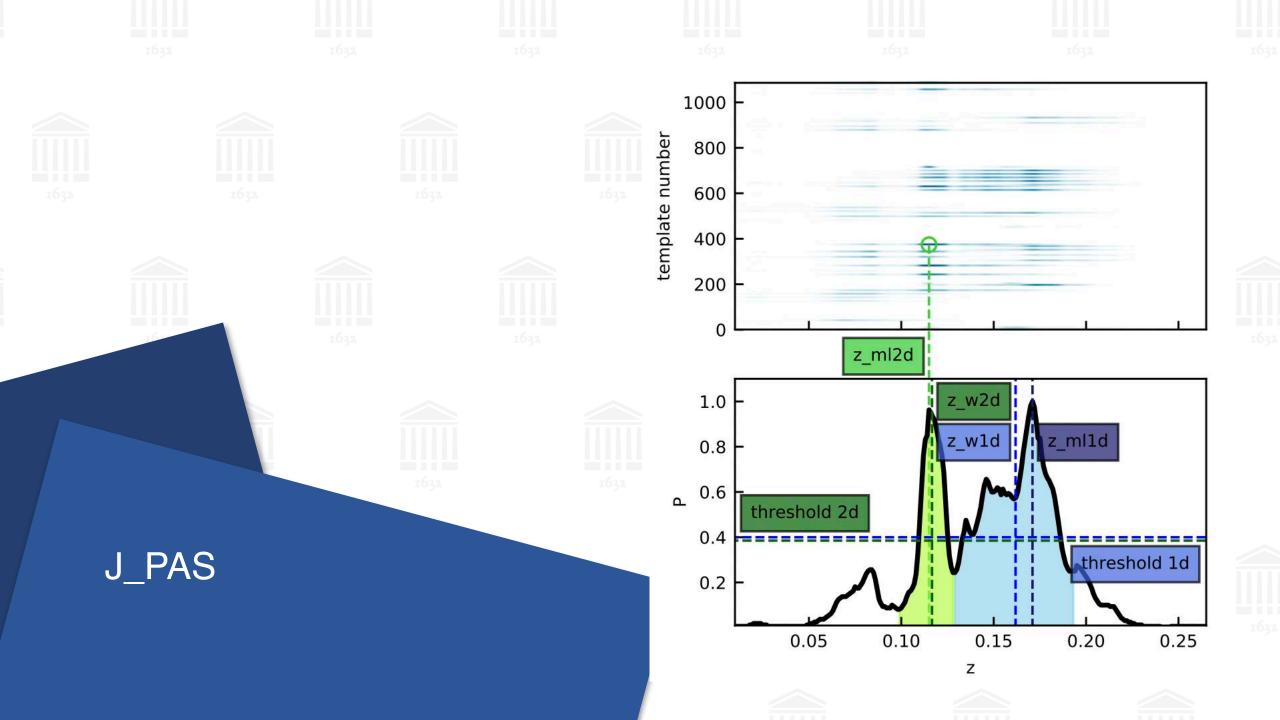


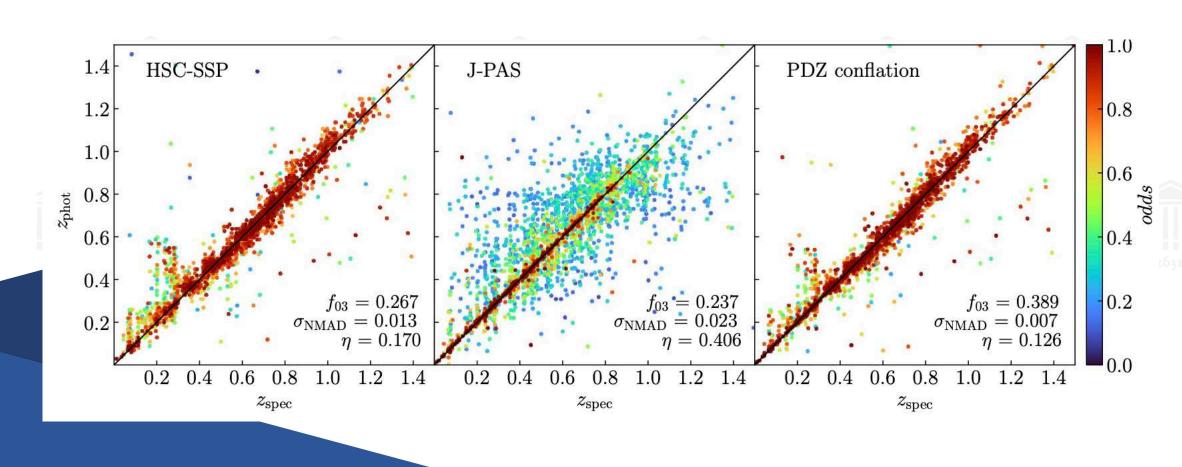


J-PAS — Javalambre Physics of the Accelerating Universe Astrophysical Survey





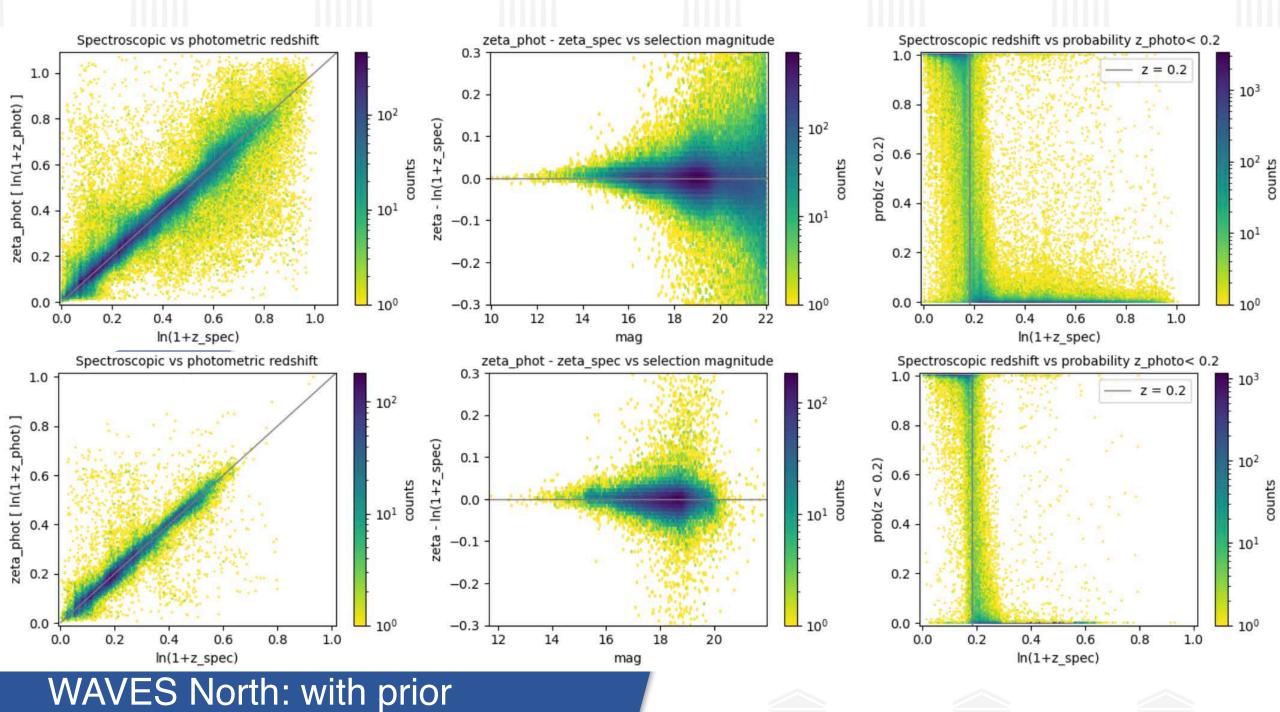




J_PAS









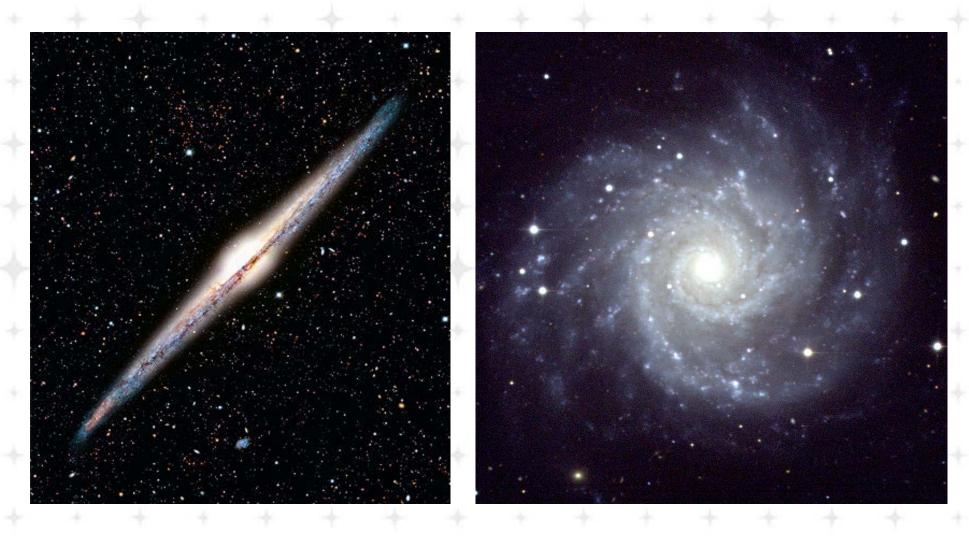
Extra slides





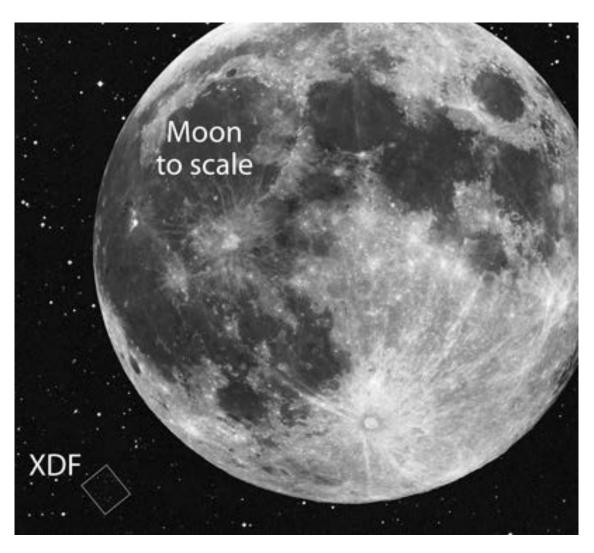
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Is this the same galaxy?



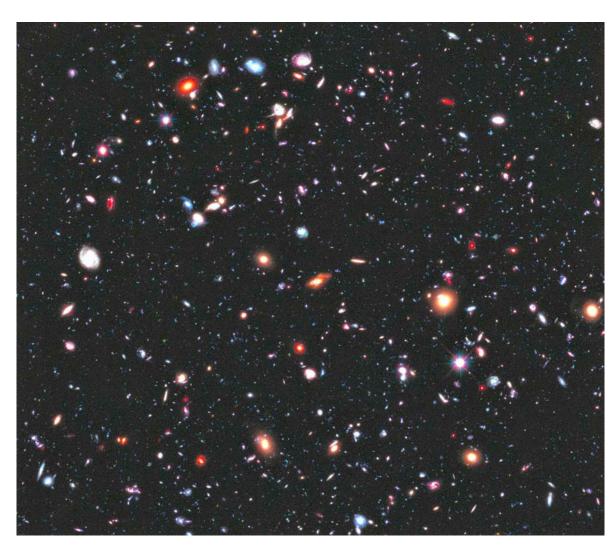


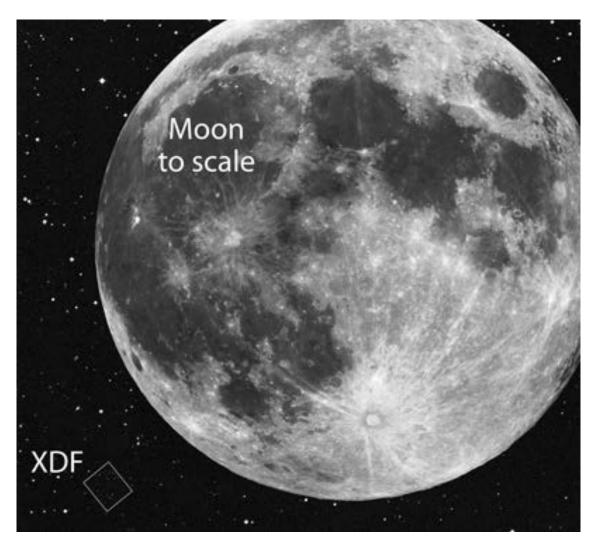
How empty is Univerre?





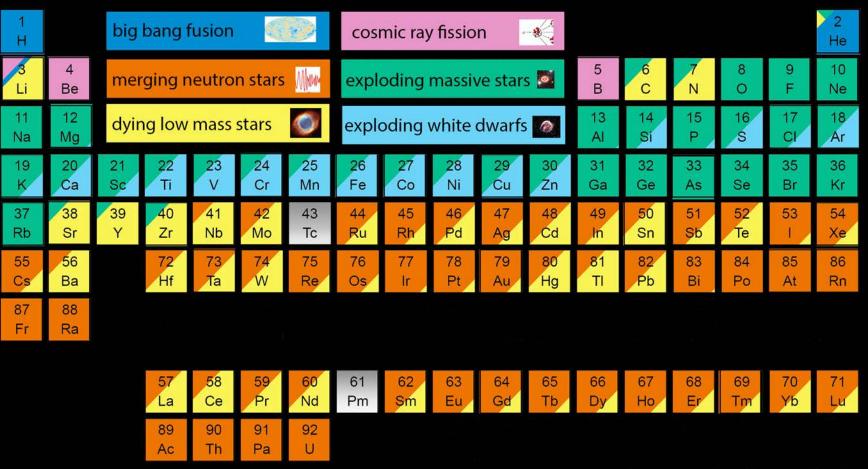
How empty is Univerre?





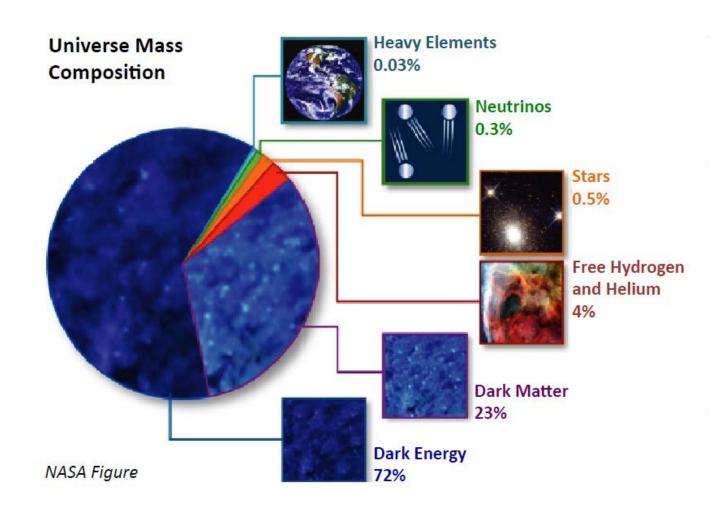
Source: ESA/Hubble

The Origin of the Solar System Elements

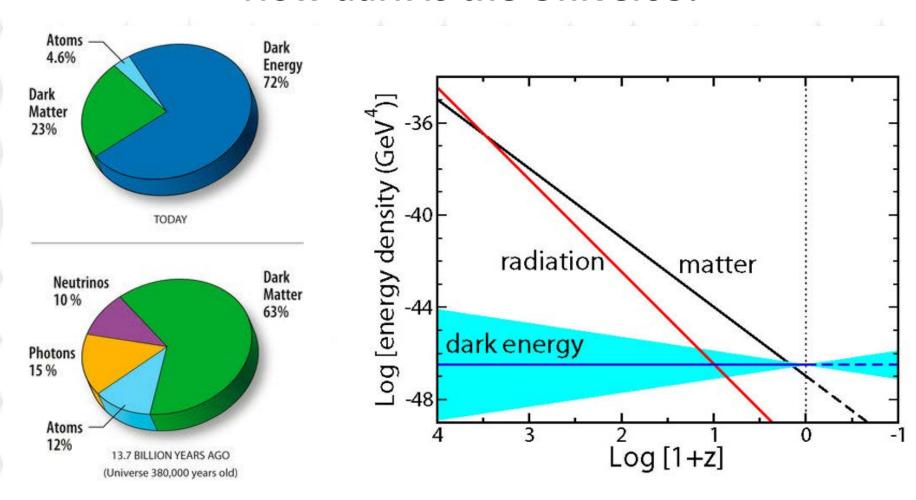


Astronomical Image Credits: ESA/NASA/AASNova

How dark is the Universe?



How dark is the Universe?



$$B_3(x) = \frac{|x-2|^3 - 4|x-1|^3 + 6|x|^3 - 4|x+1|^3 + |x+2|^3}{12}.$$



